

From last time: $J'' + R_V J = 0 \iff \begin{cases} J' = S J \\ S' + S^2 + R_V = 0 \end{cases} \quad (S = \nabla V)$

Thm. Let $R_1, R_2: \mathbb{R} \rightarrow \text{Sym}^2 E$ be smooth curves with $R_1(t) \geq R_2(t), \forall t$.
 Let $S_i: [t_0, t_i) \rightarrow \text{Sym}^2 E$ be the maximal solutions to $S_i' + S_i^2 + R_i = 0$.
 If $S_1(t_0) \leq S_2(t_0)$, then $t_1 \leq t_2$ and $S_1(t) \leq S_2(t)$ for all $t \in [t_0, t_1)$.

Next, we apply the above to get a comparison of lengths of Jacobi fields:

Thm. Let $S_1, S_2: (t_0, t') \rightarrow \text{Sym}^2 E$ be smooth curves with $S_1(t) \leq S_2(t)$.
 Let $J_i: (t_0, t') \rightarrow E$ be nonzero sol. to $J_i' = S_i J_i$. Then $t \mapsto \frac{\|J_1(t)\|}{\|J_2(t)\|}$
 is nonincreasing. Moreover, if $\lim_{t \rightarrow t_0} \frac{\|J_1(t)\|}{\|J_2(t)\|} = 1$, then $\|J_1(t)\| \leq \|J_2(t)\|$
 for all $t \in (t_0, t')$. Equality holds for some $t_* \in (t_0, t')$ if and only if
 $J_i = j \cdot v_i$ on $[t_0, t']$ for some $v_i \in E$ with $S_i v_i = \lambda v_i, j' = \lambda j$,
 and $S_1 \leq \lambda \text{Id} \leq S_2$.

Pf. Since $\|J_i(t)\|$ is smooth, we can differentiate:

$$\frac{\|J_i\|'}{\|J_i\|} = \frac{1}{\|J_i\|} \frac{1}{2\sqrt{\langle J_i, J_i \rangle}} 2 \langle J_i', J_i \rangle = \frac{\langle J_i', J_i \rangle}{\|J_i\|^2} = \frac{\langle S_i J_i, J_i \rangle}{\|J_i\|^2} \in [\lambda_{\min}(S_i), \lambda_{\max}(S_i)]$$

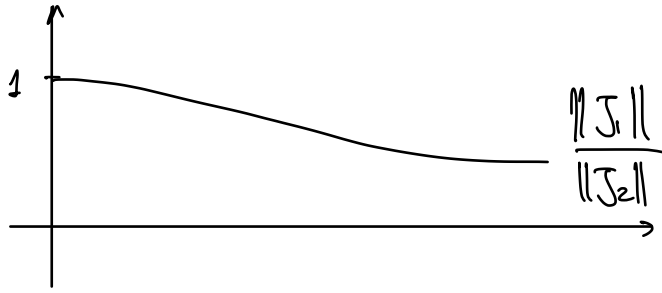
min. and max eigenvalues of $S_i \in \text{Sym}^2 E$.

$$\text{Thus } (\log \|J_1\|)' = \frac{\|J_1\|'}{\|J_1\|} \leq \lambda_{\max}(S_1) \leq \lambda_{\min}(S_2) \leq \frac{\|J_2\|'}{\|J_2\|} = (\log \|J_2\|)'$$

\uparrow
 $S_1 \leq S_2$

$$\text{i.e. } \left(\log \frac{\|J_1\|}{\|J_2\|} \right)' \leq 0 \quad \text{so } \frac{\|J_1\|}{\|J_2\|} \text{ is non-increasing.}$$

By monotonicity, if $\|J_1\| = \|J_2\|$ at $t = t_0$, and $t = t_*$. Then $\|J_1\| = \|J_2\|$, $\forall t \in (t_0, t_*)$ and hence $J_i' = S_i J_i = \lambda J_i$, from which the stated conclusions follow. \square



The following corollaries are originally due to Berger and Rauch:

Thm (Rauch I). Suppose J_i are sol to $J_i'' + R_i J_i = 0$ with $R_1 \geq R_2$ and $J_i(0) = 0$, $\|J_1'(0)\| = \|J_2'(0)\|$. Then $\|J_1\| \leq \|J_2\|$ up to the first zero of J_1 .

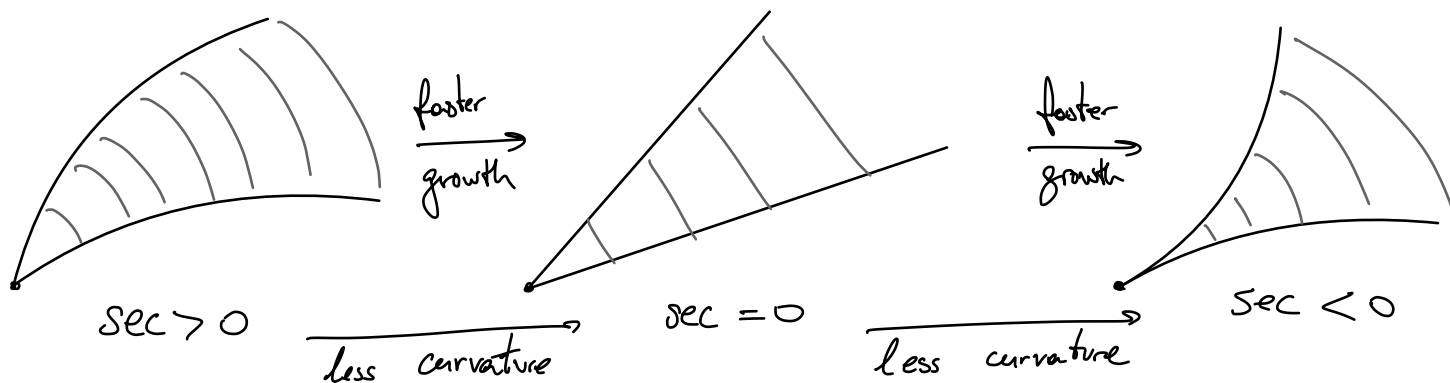
Thm (Rauch II). Suppose J_i are sol to $J_i'' + R_i J_i = 0$ with $R_1 \geq R_2$ and $J_i'(0) = 0$, $\|J_1(0)\| = \|J_2(0)\|$. Then $\|J_1\| \leq \|J_2\|$ up to the first zero of J_1 .

Both Rauch I and II follow from comparison theorems above; namely $R_1(t) \geq R_2(t)$ and $S_1(0) = S_2(0)$ give $S_1(t) \leq S_2(t)$ for all $t \in (0, t_1)$. Then:

Rauch I: use singular initial condition " $S_i(0) = \infty$ ", ie, $S_i(t) \sim \frac{1}{t} \text{Id}$ as $t \downarrow 0$
 $J_i' = S_i J_i \Rightarrow t J_i' \sim J_i$ as $t \downarrow 0 \Rightarrow J_i(0) = 0$
 $\|J_1'(0)\| = \|J_2'(0)\| \Rightarrow \lim_{t \downarrow 0} \frac{\|J_1(t)\|}{\|J_2(t)\|} = \lim_{t \downarrow 0} \frac{t \|J_1'(t)\|}{t \|J_2'(t)\|} = 1$. Apply Thm. \square

Rauch II: use initial condition $S_i(0) = 0$
 $J_i' = S_i \cdot J_i \Rightarrow J_i'(0) = 0$.
 $\|J_1(0)\| = \|J_2(0)\| \Rightarrow \lim_{t \downarrow 0} \frac{\|J_1(t)\|}{\|J_2(t)\|} = 1$. Apply Thm. \square

Picture to have in mind from Rauch I:

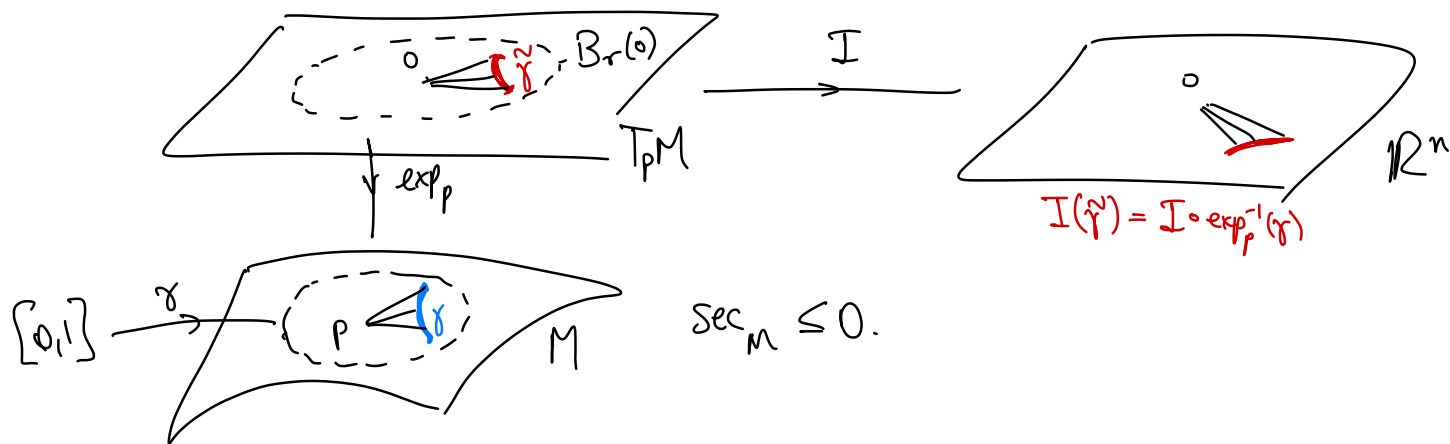


(We knew this for $t \approx 0$ from Taylor Series expansion of $\|J(t)\|^2$ at $t=0$, now this is known for $0 \leq t \leq t_1$ where t_1 is the first conjugate time.)

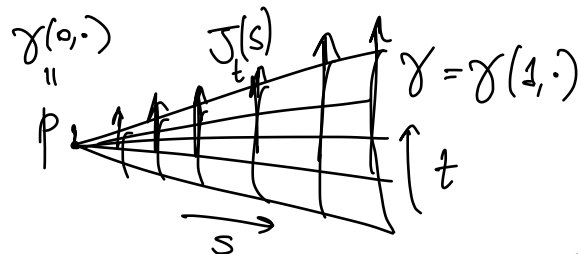
Application of Rauch I:

Cor: Let (M^n, g) be a complete Riem. mfd with $\sec \leq 0$, and $r > 0$ s.t. $\exp_p : B_r(0) \rightarrow M$ is a diffeom. onto its image. Fix a linear isometry $I : T_p M \rightarrow \mathbb{R}^n$. Given $\gamma : [0, 1] \rightarrow \exp_p(B_r(0))$, we have

$$\text{length}_g(\gamma) \geq \text{length}_{\mathbb{R}^n}(I \circ \exp_p^{-1}(\gamma)).$$



Pf: Let $\tilde{\gamma} = \exp_p^{-1} \gamma$, and consider the "rectangle" $\gamma(s, t) = \exp_p s \tilde{\gamma}(t)$



For fixed t , $s \mapsto \gamma(s, t)$ is a geodesic, and $J_t(s) = \frac{\partial}{\partial t} \gamma(s, t)$ is a Jacobi field along $s \mapsto \gamma(s, t)$, with $J_t(0) = 0$ and $J_t(1) = \dot{\gamma}(t)$. Since $\sec_M \leq 0$, by Rauch I,


$$\|J_t(s)\| \geq s \|J_t'(0)\| \text{ so } \text{length}_g(\gamma) = \int_0^1 \|\dot{\gamma}(t)\| dt = \int_0^1 \|J_t(1)\| dt$$

$\xrightarrow{s=1}$

$$\stackrel{\textcircled{*} \text{ length of comparison Jacobi field in } \mathbb{R}^n}{\geq} \int_0^1 \|J_t'(0)\| dt = \text{length}_{\mathbb{R}^n}(I \circ \exp_p^{-1} \gamma)$$

$$\begin{aligned} \text{Indeed, } J_t'(0) &= \frac{D}{ds} J_t(s) \Big|_{s=0} = \frac{D}{ds} \frac{\partial}{\partial t} \exp_p s \dot{\gamma}(t) \Big|_{s=0} \\ &= \frac{D}{dt} \frac{\partial}{\partial s} \exp_p s \dot{\gamma}(t) \Big|_{s=0} = \frac{D}{dt} \underbrace{d(\exp_p)_0}_{\text{id}} \dot{\gamma}(t) = \dot{\gamma}'(t) \end{aligned}$$

$$\text{and so } \text{length}_{\mathbb{R}^n}(I \circ \exp_p^{-1} \gamma) = \int_0^1 \left\| \underbrace{\frac{\partial}{\partial t} I \circ \exp_p^{-1}(\gamma)}_{\dot{\gamma}} \right\| dt = \int_0^1 \|J_t'(0)\| dt. \quad \square$$

$\textcircled{*}$ In \mathbb{R}^n , the Jacobi equation $J'' = 0$ has solutions $J(s) = J(0) + s J'(0)$, so Jacobi fields with $J(0) = 0$ are given by $J(s) = s J'(0)$. 

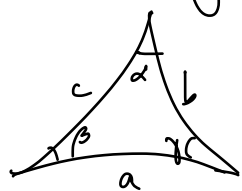
Rmk: Reasoning as above, Rauch I gives a more refined estimate

$$\|J(t)\| \geq t \|J'(0)\| > 0$$

for Jacobi fields with $J(0) = 0$ on manifolds with $\sec \leq 0$, compared to our earlier observation (a crucial step in the proof of Cartan-Hadamard Thm) that $J(t) \neq 0$, $\forall t > 0$; cf. Remark in p.2 of Lectures3.pdf.

Def. A geodesic triangle is a triple of minimizing geodesics with endpoints that match pairwise (as in a triangle).

Cor: A geodesic triangle on a complete manifold with $\sec \leq 0$ satisfies

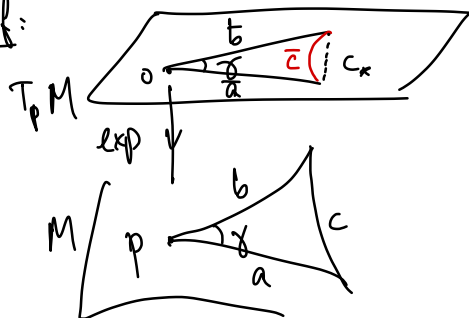


$$(i) \quad l(c)^2 \geq l(a)^2 + l(b)^2 - 2l(a)l(b)\cos\gamma \quad (l = \text{length})$$

$$(ii) \quad \alpha + \beta + \gamma \leq \pi$$

If $\sec < 0$, then get strict inequalities.

Pf:



Let $\bar{a}, \bar{b}, \bar{c}$ in $T_p M$ be such that

$$a = \exp_p \bar{a}, \quad b = \exp_p \bar{b}, \quad c = \exp_p \bar{c}$$

Note that \bar{a} and \bar{b} are straight line segments (\exp_p is radial isometry); with $l(\bar{a}) = l(a)$ and $l(\bar{b}) = l(b)$. Let c_* be the straight line segment with same endpoints as \bar{c} , so $l(\bar{c}) \geq l(c_*)$. By the Application of Rauch I, $l(c) \geq l(\bar{c}) \geq l(c_*)$. Thus, altogether:

Law of cosines in $T_p M \cong \mathbb{R}^n$

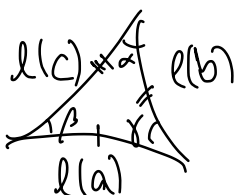
$$l(c)^2 \geq l(c_*)^2 \stackrel{\text{Law of cosines}}{=} l(\bar{a})^2 + l(\bar{b})^2 - 2l(\bar{a})l(\bar{b})\cos\gamma$$

$$\text{Gauss Lemma} \stackrel{\text{Law of cosines}}{=} l(a)^2 + l(b)^2 - 2l(a)l(b)\cos\gamma.$$

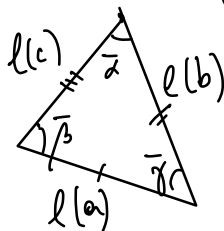
To compare angles, since $l(a), l(b), l(c)$ satisfy the triangle inequalities (b/c every geodesic is minimizing in $\sec \leq 0$, i.e., $l(a), l(b), l(c)$ achieve distances) we can build a comparison triangle in \mathbb{R}^2 , with same side lengths, but possibly different angles, say $\bar{\alpha}, \bar{\beta}, \bar{\gamma}$. Then, from the above:

$$\begin{aligned} l(a)^2 + l(b)^2 - 2l(a)l(b)\cos\gamma &\leq l(c)^2 \\ &= l(a)^2 + l(b)^2 - 2l(a)l(b)\cos\bar{\gamma} \end{aligned}$$

$$\Rightarrow \cos\gamma \geq \cos\bar{\gamma} \Rightarrow \gamma \leq \bar{\gamma}$$



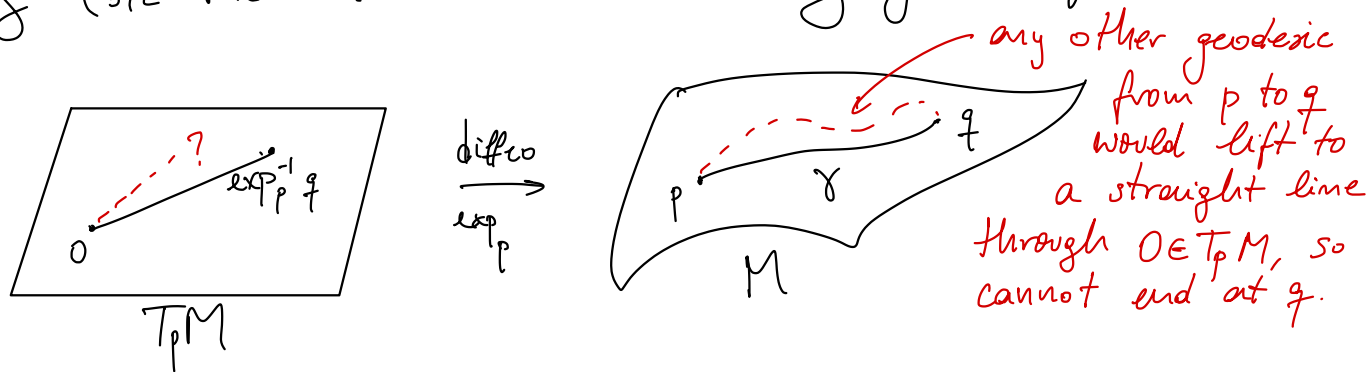
in M



in \mathbb{R}^2

Same for α, β and get $\alpha + \beta + \gamma \leq \bar{\alpha} + \bar{\beta} + \bar{\gamma} = \pi$. \square

Rmk: If (M^n, g) is a complete Riem. mfld with $\pi_1 M = \{1\}$ and $\sec \leq 0$, then by Cartan-Hadamard $\exp_p: T_p M \rightarrow M$ is a diffeo, so given any $q \in M$ there is a unique geodesic joining p and q , which is hence minimizing (b/c there exists some minimizing geodesic by Hopf-Rinow).



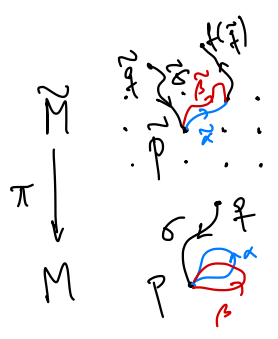
Thus, if M is complete, $\pi_1 M = \{1\}$, and $\sec \leq 0$, then the above facts about geodesic triangles hold for any triangles with geodesic sides (b/c the sides are automatically minimizing.)

Lecture 21 4/17/2024

Def: (M, g) closed Riem. mfld, (\tilde{M}, \tilde{g}) universal covering.
A deck transformation $f: \tilde{M} \rightarrow \tilde{M}$ is a translation along the geodesic $\tilde{\gamma}$ in \tilde{M} if $f(\tilde{\gamma}) = \tilde{\gamma}$. Note: If $f \neq \text{id}$, then $f(\tilde{\gamma}(t)) = \tilde{\gamma}(t+a)$.

From basic topology: $\pi_1(M) \cong \text{Aut}(\tilde{M}) = \{f: \tilde{M} \rightarrow \tilde{M} : \text{deck transformation}\}$

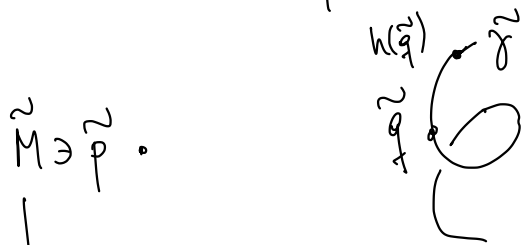
$[\alpha] \in \pi_1(M, p) \mapsto (f_{\alpha, p}: \tilde{M} \rightarrow \tilde{M}) \in \text{Aut}(\tilde{M})$
 $f_{\alpha, p}(\tilde{q}) = \text{endpoint of lift of } \sigma^{-1} \alpha \sigma \text{ to } \tilde{M}, \text{ starting at } \tilde{q}.$



Recall: curves in M are homotopic \Leftrightarrow lifts to \tilde{M} have same endpoint
so the above is well-defined.

Prop. Given a deck transformation $f: \tilde{M} \rightarrow \tilde{M}$, there exists a geodesic $\tilde{\gamma}$ in \tilde{M} s.t. f is a translation along $\tilde{\gamma}$.

Pf. $f = f_{\alpha, p}$ for some $\alpha \in \pi_1(M, p)$. Let $\gamma \sim \alpha$ be a closed geodesic. Then



$h = f_{\gamma, \tilde{\gamma}} \in \text{Aut}(\tilde{M})$ is s.t. $h(\tilde{\gamma}) = \tilde{\gamma}$; by construction.

Claim: $f = h$.

Since h, f are deck transformations, suffices to show $h(\tilde{q}) = f(\tilde{q})$.

As α, γ are freely homotopic, it follows

$\sigma^{-1} \alpha \sigma$ is homotopic to γ rel. \tilde{q} .

(as elements of $\pi_1(M, \tilde{q})$.) So the

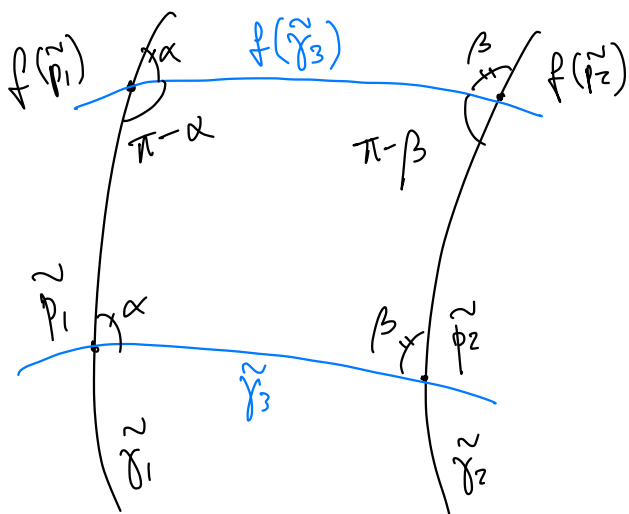
endpoints of their lifts are the same, i.e., $h(\tilde{q}) = f(\tilde{q})$ so $h = f$ hence $f(\tilde{\gamma}) = \tilde{\gamma}$. \square

Lemma. If (M, g) is a closed mfd with $\sec < 0$, then a deck transformation $f: \tilde{M} \rightarrow \tilde{M}$, $f \neq \text{id}$ is a translation along a unique geodesic $\tilde{\gamma}$ in \tilde{M} .

Pf. Suppose $\tilde{\gamma}_1$ and $\tilde{\gamma}_2$ are geodesics in \tilde{M} s.t. f is a translation along $\tilde{\gamma}_i$. Then, if $\tilde{p} \in \tilde{\gamma}_1 \cap \tilde{\gamma}_2$, we have $\tilde{p} \neq f(\tilde{p}) \in \tilde{\gamma}_1 \cap \tilde{\gamma}_2$, but this contradicts injectivity of $\exp_{\tilde{p}}$. $\left(\begin{array}{l} f \neq \text{id} \\ \Rightarrow f \text{ has no fixed pts.} \end{array} \right)$

Thus $\tilde{\gamma}_1 \cap \tilde{\gamma}_2 = \emptyset$.

by Cartan-Hadamard, $\exp_{\tilde{p}}: T_{\tilde{p}}\tilde{M} \rightarrow \tilde{M}$ is a diffeo



Let $\tilde{p}_i \in \tilde{\gamma}_i$ and $\tilde{\gamma}_3$ be a minimizing geodesic from \tilde{p}_1 to \tilde{p}_2 . As f is an isometry of \tilde{M} , the angles α, β in the diagram are the same. Subdividing this quadrangle into two triangles Δ_1, Δ_2 it follows that

$$\sum_{\text{int. angles}} \Delta_1 + \sum_{\text{int. angles}} \Delta_2 \geq 2\pi$$

So $\sum_{\text{int. angle}} \Delta_i \geq \pi$ for $i=1$ or 2 , contradicting Con. from last □

Lecture that $\sum_{\text{int. angles}} \Delta < \pi$ if $\text{sec} < 0$.

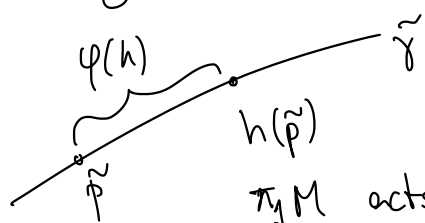
Lemma. If (M, g) is a closed mfd with $\text{sec} < 0$, then commuting deck transformations are translations along the same geodesic.

Pf. If $f_1, f_2: \tilde{M} \rightarrow \tilde{M}$ are as above, with $f_i(\tilde{\gamma}_i) = \tilde{\gamma}_i$, then $f_2(f_1(\tilde{\gamma}_2)) = f_1(f_2(\tilde{\gamma}_2)) = f_1(\tilde{\gamma}_2)$ so f_2 preserves $f_1(\tilde{\gamma}_2)$ hence $f_1(\tilde{\gamma}_2) = \tilde{\gamma}_2$. By uniqueness proved above, $\tilde{\gamma}_1 = \tilde{\gamma}_2$. □

Thm (Preissmann, 1943). If (M^n, g) is a closed Riem. mfd with $\text{sec} < 0$ and $H < \pi_1 M$ is Abelian, $H \neq \{1\}$, then $H \cong \mathbb{Z}$.

Pf. Let $H < \pi_1 M$ be Abelian, and $\tilde{\gamma}$ be the geodesic in \tilde{M} along which every $h \in H$ is a translation. Recall (see Remark at end of last lecture) that given two points in \tilde{M} there is a unique geodesic (hence minimizing) joining them. For $\tilde{p} \in \tilde{\gamma}$ and define $\varphi: H \rightarrow \mathbb{R}$, $\varphi(h) = \pm \text{dist}(\tilde{\gamma}, h(\tilde{p}))$, according to $h(\tilde{p})$ being before/after \tilde{p} along $\tilde{\gamma}$. Then φ is a group homomorphism and injective, so

the subgroup $\varphi(H) < \mathbb{R}$ is either dense or isomorphic to \mathbb{Z} . It cannot be dense because $\pi_1 M$ acts properly discontinuously on \tilde{M} . □



Cor. If M_1, M_2 are closed manifolds, then $M_1 \times M_2$ does not admit any metric with $\sec < 0$.

Pf. Suppose $(M_1 \times M_2, g)$ has $\sec < 0$; in particular, by Cartan-Hadamard,

$\widetilde{M_1 \times M_2} \cong \widetilde{M_1} \times \widetilde{M_2} \cong \mathbb{R}^n$ so $\pi_1 M_i \neq \{1\}$ for $i=1,2$. Indeed, if, say $\pi_1 M_1 = \{1\}$, then $\widetilde{M_1} \times \widetilde{M_2} \cong M_1 \times \widetilde{M_2} \neq \mathbb{R}^n$ because M_1 is closed. Let $h_i \in \pi_1 M_i$ be nontrivial elements and $\langle h_i \rangle$ the corresponding cyclic subgroups. Then $H = \langle h_1 \rangle \oplus \langle h_2 \rangle$ is an Abelian subgroup of $\pi_1 M$ that is not isomorphic to \mathbb{Z} . \square

E.g., T^n does not have any metric with $\sec < 0$ } But they have metrics with $\sec \leq 0$!
 $\sum^2 \times S^1$ does not have any metric with $\sec < 0$

e.g., \uparrow
 closed surface of genus ≥ 2 Rmk. Byers showed that if a closed manifold (M, g) with $\sec < 0$ has $H < \pi_1 M$ a nontrivial solvable subgroup, then $H \cong \mathbb{Z}$. Moreover, $\pi_1 M$ does not admit finite-index cyclic subgroups.

Rmk. It is unknown if any $M_1 \times M_2$ where M_i are closed, $\pi_1 M_i = \{1\}$, can admit metrics with $\sec > 0$. The case $M_1 = M_2 = S^2$ is known as the Hopf Question.

Rmk. The analogous question for $\sec > 0$ was proposed by Chern in 1965:

If (M, g) is a closed Riem. mfd w/ $\sec > 0$, and $H < \pi_1 M$ is Abelian, then is H cyclic? By Synge, the answer is affirmative in even dimensions.

Ravi Shankar (1998) found infinitely many counter-examples in dimension 7, as there are homogeneous spaces M^7 with $\sec > 0$ and a free action by $\mathbb{Z}_2 \oplus \mathbb{Z}_2$ which is isometric. Thus, $M^7 / \mathbb{Z}_2 \oplus \mathbb{Z}_2$ is a closed manifold with $\sec > 0$ and fundamental group $\mathbb{Z}_2 \oplus \mathbb{Z}_2$.

Comparison theorems for sec: Rauch I, II \rightsquigarrow Preissmann, Cartan-Hadamard, Myers, Synge, ...

Toponogov \rightsquigarrow Gramov's bounds on generators of π_1 , total Betti #, ... Alexandrov geometry
 maybe later? \nearrow \nwarrow also with second variation of length/energy.

Comparison theorem for Ric: Bishop Volume Comparison \rightsquigarrow Milnor (π_1 has polynomial growth)
 Rigidity in Myers, (today)
 Gramov's compactness theorem, ...

Recall Riccati equation:

$$S' + S^2 + R_V = 0 \quad (\text{in } \text{Sym}^2 E) \quad \rightsquigarrow \quad \text{tr } S' + \text{tr}(S^2) + \text{Ric}(V) \stackrel{\otimes}{=} 0 \quad (\text{in } \mathbb{R})$$

this is not a function of $\text{tr } S$...

like the actual shape operator...

Since $S(V) = \nabla_V V = 0$, can restrict S to V^\perp , $S: V^\perp \rightarrow V^\perp$, \checkmark


and $S \in \text{Sym}^2 V^\perp$. Let $a = \frac{\text{tr } S}{n-1}$, and note that

$$S = a \text{Id} + S_0, \quad \text{where } \text{tr } S_0 = 0. \quad \text{"free-free part"}$$

So $\langle S_0, I \rangle = 0$. \leftarrow recall $\langle A, B \rangle = \text{tr } AB$

Then $\text{tr}(S^2) = \|S\|^2 = a^2 \| \text{Id} \|^2 + \|S_0\|^2 = (n-1)a^2 + \|S_0\|^2$ so \circledast

gives $a' + a^2 + r = 0$, where $r = \frac{1}{n-1} (\|S_0\|^2 + \text{Ric}(V)) \geq \frac{\text{Ric}(V)}{n-1}$

Rmk: Geometrically, $a(t) = \frac{H}{n-1}$ where $H = \text{tr } S$ is the mean curvature of S_t . 

Thm. Suppose $S: [t_0, t_1) \rightarrow \text{Sym}^2 V^\perp$ is the maximal solution to $S' + S^2 + R = 0$, where $R: \mathbb{R} \rightarrow \text{Sym}^2 V^\perp$ is given. Suppose $\exists K \in \mathbb{R}$ s.t.

(i) $\text{tr } R \geq (n-1)K$

(ii) $\text{tr } S(t_0) \leq (n-1)\bar{a}(t_0)$

where $\bar{a}: [t_0, t_2) \rightarrow \mathbb{R}$ is the maximal solution to $\bar{a}' + \bar{a}^2 + K = 0$. Let $a = \frac{\text{tr } S}{n-1}$

Then $t_1 \leq t_2$ and $a(t) \leq \bar{a}(t)$ for all $t \in [t_0, t_1)$.

Pf: Apply ODE comparison from Lectures 19-20:

Thm. Let $R_1, R_2: \mathbb{R} \rightarrow \text{Sym}^2 E$ be smooth curves with $R_1(t) \geq R_2(t), \forall t$.
 Let $S_i: [t_0, t_i) \rightarrow \text{Sym}^2 E$ be the maximal solutions to $S_i' + S_i^2 + R_i = 0$.
 If $S_1(t_0) \leq S_2(t_0)$, then $t_1 \leq t_2$ and $S_1(t) \leq S_2(t)$ for all $t \in [t_0, t_1)$.

setting $E = \mathbb{R}$, $R_1 = r$, $R_2 = k$, so $(i) \Rightarrow r \geq k \Rightarrow R_1 \geq R_2$

$$S_1' + S_1^2 + R_1 = 0 \Leftrightarrow a' + a^2 + r = 0$$

$$S_2' + S_2^2 + R_2 = 0 \Leftrightarrow \bar{a}' + \bar{a}^2 + k = 0.$$

□

Remark: Above result remains true if \bar{a} has a pole at t_0 ; namely

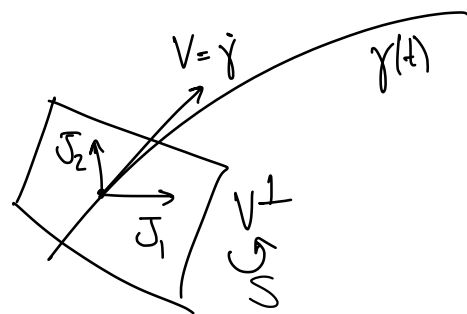
$$S(t) \sim \frac{1}{t-t_0} \text{Id}, \quad \bar{a} = \frac{S n_k'}{S n_k} \quad \text{where} \quad \begin{cases} S n_k'' + K S n_k = 0 \\ S n_k(t_0) = 0 \\ S n_k'(t_0) = 1. \end{cases}$$

Let J_1, \dots, J_{n-1} be Jacobi fields along γ that form a basis of solutions to

$$J' = S J \quad (S: V^\perp \rightarrow V^\perp)$$

and set $j = \det(J_1, J_2, \dots, J_{n-1})$.

all identified via parallel transport



$$j' = \det(J_1', J_2, \dots, J_{n-1}) + \det(J_1, J_2', J_3, \dots, J_{n-1}) + \dots + \det(J_1, \dots, J_{n-1}')$$

$$= \det(S J_1, J_2, \dots, J_{n-1}) + \det(J_1, S J_2, J_3, \dots, J_{n-1}) + \dots + \det(J_1, \dots, S J_{n-1})$$

$$= \text{tr } S \cdot \det(J_1, \dots, J_{n-1}) = \text{tr } S \cdot j$$

or: $d(\det)_I X = \text{tr } X$; more generally, if A is invertible, $d(\det)_A X = (\det A) \text{tr}(A^{-1} X)$

so we have $j' = (n-1) a j$

Let $j(t) = \det A(t)$, where $A(t) = (J_1(t), \dots, J_{n-1}(t))$.

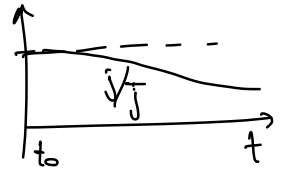
$$j'(t) = d(\det)_{A(t)} A'(t) = (\det A(t)) \text{tr}(A(t)^{-1} A'(t))$$

$$= j(t) \cdot \text{tr}(A^{-1}(t) \cdot S(t) \cdot A(t)) = (\text{tr } S) \cdot j$$

Thm. Let $S: [t_0, t_1) \rightarrow \text{Sym}^2 V^\perp$ and $a = \frac{1}{n-1} \text{tr } S$ be s.t. $a \leq \bar{a}$, and $j' = (n-1)a_j$. Choose \bar{j} s.t. $\bar{j}' = (n-1)\bar{a}_j$. Then j/\bar{j} is nonincreasing.

Pf: Once again, apply ODE comparison from before!

$$(n-1)a \leq (n-1)\bar{a} \Rightarrow \left(\log \frac{j}{\bar{j}} \right)' \leq 0 \Rightarrow \frac{j}{\bar{j}} \text{ nonincreasing}$$



Thm (Bishop Volume Comparison). Let (M^n, g) be a Riem. mfd with $\text{Ric} \geq (n-1)K$ and \bar{M} be the simply-connected Riem. mfd with $\text{sec}_{\bar{M}} \equiv K$. Then $\forall p \in M$, $\text{Vol}(B_r(p)) \leq \text{Vol}(\bar{B}_r)$, where $B_r(p) \subset M$ and $\bar{B}_r \subset \bar{M}$ are balls of radius r . Moreover, equality holds if and only if $B_r(p) \cong_{\text{isom}} \bar{B}_r$.

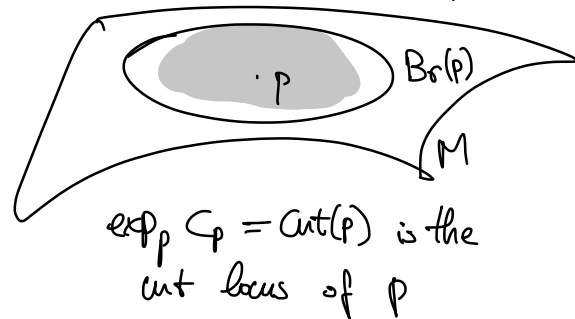
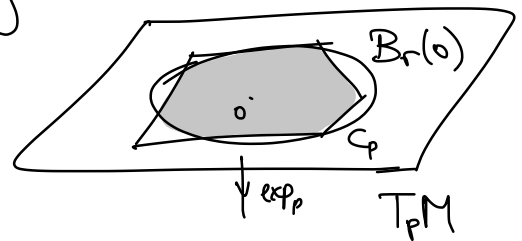
Pf: We will show that $r \mapsto \frac{\text{Vol}(B_r(p))}{\text{Vol}(\bar{B}_r)}$ is nonincreasing; the conclusion

follows since $\lim_{r \rightarrow 0} \frac{\text{Vol}(B_r(p))}{\text{Vol}(\bar{B}_r)} = 1$ because both approach Euclidean balls as $r \rightarrow 0$.

Let $\text{cut}(v) = \max\{t_* > 0 : \exp_{p_*} tv \text{ is min. geod. on } [0, t_*]\}$

and $C_p = \{tv : t \leq \text{cut}(v), \|v\|=1\} \subset T_p M$. Then

$\exp_p: C_p \rightarrow M$ is a diffeom. onto its image, so:



$$\text{Vol}(B_r(p)) = \int_{B_r(p)} 1 \, d\text{vol} = \int_{\exp_p(B_r(o) \cap C_p)} 1 \, d\text{vol}$$

$$\stackrel{\text{Change of variables formula}}{=} \int_{B_r(o) \cap C_p} \det(d(\exp_p)_u) \, du$$

$$\stackrel{\text{Polar coord.}}{=} \int_{S^{n-1}(1)} \int_0^{r(v)} \det(d(\exp_p)_{tv}) t^{n-1} dt dv$$

Recall:

$$B_r(p) = \exp_p(B_r(o)) = \exp_p(B_r(o) \cap C_p)$$

where $r(v) = \min\{r, \text{cut}(v)\}$ for $v \in T_p M$, $\|v\|=1$, i.e. $v \in S^{n-1}(1) \subset T_p M$.

Since $d(\exp_p)_{tv} e_i = \frac{1}{t} (d(\exp_p)_{tv} t e_i) = \frac{1}{t} J_i(t)$ is the Jacobi field along $t \mapsto \exp_p tv$ with $J_i(0) = 0$ and $J_i'(0) = e_i$, it follows that

$$\det(d(\exp_p)_{tv}) = \frac{1}{t^{n-1}} \det(J_1(t), \dots, J_{n-1}(t)) \quad \text{and hence:}$$

$$\text{Vol}(Br(p)) = \int_{S^{n-1}(1)} \int_0^{r(v)} \underbrace{\det(J_1(t), \dots, J_{n-1}(t))}_{\hat{j}_v(t)} dt dv$$

if needed, extend $j_v(t)$ as $j_v(t) = 0$ for $t > \text{cut}(v)$.

By previous result, $j_v(t)/\bar{J}(t)$ is nonincreasing on $[0, r]$, where

$\bar{J}(t) = \det(\bar{J}_1, \dots, \bar{J}_{n-1})$, for corresponding Jacobi fields \bar{J}_i on \bar{M} .

Set $q(t) = \frac{1}{\text{Vol}(S^{n-1}(1))} \int_{S^{n-1}(1)} \frac{j_v(t)}{\bar{J}(t)} dv$, which is also non-increasing

(because it is an average of nonincreasing quantities). As before,

$$\text{Vol}(\bar{B}r) = \int_{S^{n-1}(1)} \int_0^r \overset{\substack{\text{space w/ sec} \equiv K \\ \text{is isotropic}}}{\bar{J}(t)} dt dv \stackrel{\downarrow}{=} \text{Vol}(S^{n-1}) \int_0^r \bar{J}(t) dt$$

Thus,

$$\frac{\text{Vol}(Br(p))}{\text{Vol}(\bar{B}r)} = \frac{\int_{S^{n-1}(1)} \int_0^r j_v(t) dt dv}{\text{Vol}(S^{n-1}(1)) \cdot \int_0^r \bar{J}(t) dt} \stackrel{\text{Fubini}}{=} \frac{\int_0^r q(t) \cdot \bar{J}(t) dt}{\int_0^r \bar{J}(t) dt}$$

is nonincreasing, because RHS is the \bar{J} -weighted average^(*) of the nonincreasing function $q(t)$ over growing intervals.

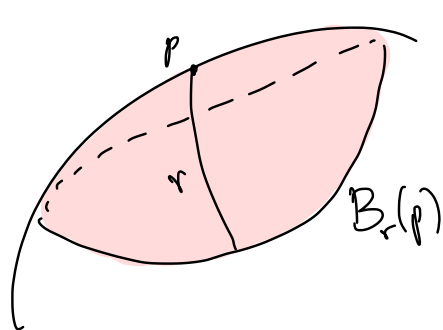
④ More explicitly: if $\phi, \psi > 0$, and $t \mapsto \frac{\phi(t)}{\psi(t)}$ is non increasing, then

$$r \mapsto \frac{\int_0^r \phi(t) dt}{\int_0^r \psi(t) dt} = \frac{\int_0^{\bar{r}} \frac{\phi(s)}{\psi(s)} ds}{\int_0^{\bar{r}} ds} \text{ is non increasing, where } \begin{cases} ds = \psi(t) dt \\ \bar{r} = s(r) \end{cases}$$

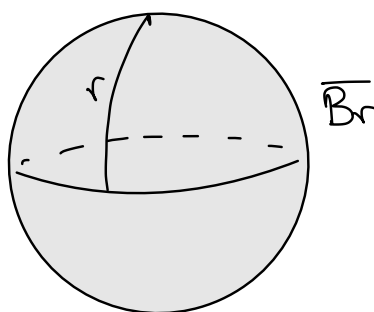
Rigidity statement follows from rigidity statements in ODE comparison:
if $\forall v \in S^{n-1}(1)$, $\forall 0 \leq t \leq r$, $j_v(t) = \bar{j}(t)$, then $a(t) = \bar{a}(t)$, for all $0 \leq t \leq r$;
so $R(t) = \bar{R}(t) = K \text{Id}$. Thus $B_r(p)$ has constant curvature $\text{sec} \equiv K$ and
is hence isometric to \bar{B}_r . \square

Remark: Similarly, one can prove $r \mapsto \frac{\text{Vol}(\partial B_r(p))}{\text{Vol}(\partial \bar{B}_r)}$ is non increasing.

Geometrically:



$$\text{Ric} \geq (n-1)K$$



$$\begin{aligned} \text{sec} &\equiv K \\ (\text{so } \text{Ric} &= (n-1)K) \end{aligned}$$

$$\text{Vol}(B_r(p)) \leq \text{Vol}(\bar{B}_r)$$

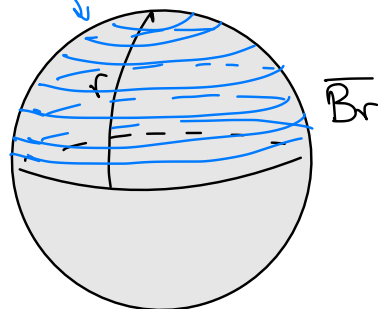
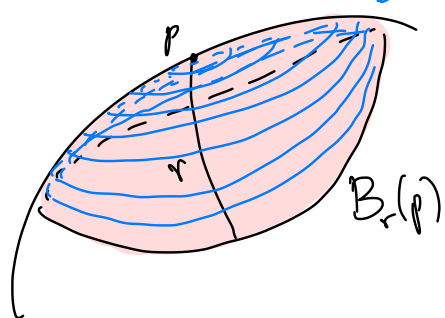
$$\begin{aligned} &= \\ &\updownarrow \\ &B_r(p) \stackrel{\text{isom}}{\cong} \bar{B}_r \end{aligned}$$

With stronger control on curvature $\text{sec} \geq K$ we know that:

so "integrating" get the above.

BUT

$\text{Ric} \geq K(n-1)$ is enough for this "integral" control.

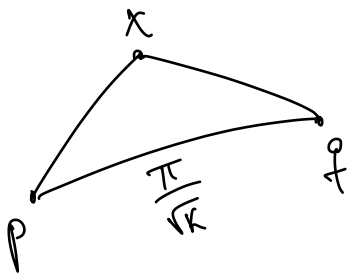


Rigidity in Myers Theorem

(Originally by Shi-Yuen Cheng, with different proof)
 ↳ student of S.S. Chern

Thm. Let (M^n, g) be a complete Riem. mfd with $\text{Ric} \geq K \cdot (n-1) > 0$ and $\text{diam}(M^n, g) = \text{diam}(S^n(1/\sqrt{K})) = \frac{\pi}{\sqrt{K}}$. Then $(M^n, g) \underset{\text{ison.}}{\cong} S^n(1/\sqrt{K})$.

Pf: Let $p, q \in M$ be points at maximal distance, i.e. $\text{dist}(p, q) = \frac{\pi}{\sqrt{K}}$. Then, for all $r > 0$, the balls $B_r(p)$ and $B_{\frac{\pi}{\sqrt{K}}-r}(q)$ are disjoint: if $d(p, x) < r$ and $d(x, q) < \frac{\pi}{\sqrt{K}} - r$, then



$$\frac{\pi}{\sqrt{K}} = d(p, q) \leq d(p, x) + d(x, q) < \frac{\pi}{\sqrt{K}}$$

so no such x can exist. Thus,

$$M \supseteq B_r(p) \dot{\cup} B_{\frac{\pi}{\sqrt{K}}-r}(q) \text{ (disjoint union)}$$

hence $\text{Vol}(M) \overset{\textcircled{*}}{\geq} \text{Vol}(B_r(p)) + \text{Vol}(B_{\frac{\pi}{\sqrt{K}}-r}(q))$. From Bishop Vol. Comp.,

$r \mapsto \frac{\text{Vol}(B_r(x))}{\text{Vol}(\overline{B_r})}$ is non increasing; in particular,

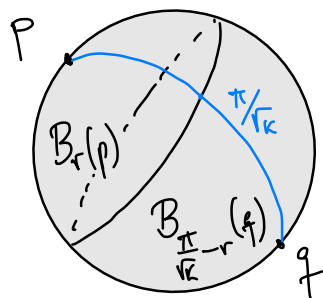
$$\frac{\text{Vol}(B_r(x))}{\text{Vol}(\overline{B_r})} \geq \frac{\text{Vol}(B_{\frac{\pi}{\sqrt{K}}}(x))}{\text{Vol}(\overline{B_{\frac{\pi}{\sqrt{K}}}})} = \frac{\text{Vol}(M)}{\text{Vol}(S^n(1/\sqrt{K}))} \quad \text{b/c} \quad \begin{cases} \overline{B_{\frac{\pi}{\sqrt{K}}}} = S^n(1/\sqrt{K}) \\ B_{\frac{\pi}{\sqrt{K}}}(x) = M \end{cases}$$

i.e. $\text{Vol}(B_r(x)) \geq \frac{\text{Vol}(M)}{\text{Vol}(S^n(1/\sqrt{K}))} \text{Vol}(\overline{B_r})$. Thus, applying this in $\textcircled{*}$:

$$\text{Vol}(M) \geq \frac{\text{Vol}(M)}{\text{Vol}(S^n(1/\sqrt{K}))} \underbrace{\left(\text{Vol}(\overline{B_r}) + \text{Vol}(\overline{B_{\frac{\pi}{\sqrt{K}}-r}}) \right)}_{\text{Vol}(S^n(1/\sqrt{K}))} = \text{Vol}(M), \text{ so all}$$

the inequalities using Bishop Vol. Comp. above are equalities. Thus, from rigidity in the equality case of Bishop Vol. Comp., we have

$$B_r(p) \underset{\text{isom}}{\cong} \overline{B_r} \text{ and } B_{\frac{\pi}{\sqrt{k}}-r}(q) \underset{\text{isom}}{\cong} \overline{B_{\frac{\pi}{\sqrt{k}}-r}}, \text{ thus } M \underset{\text{isom}}{\cong} S^n(1/\sqrt{k}).$$



$$M \underset{\text{isom}}{\cong} S^n(1/\sqrt{k})$$

Indeed, there is no room for any $M \setminus (\overline{B_r(p)} \cup \overline{B_{\frac{\pi}{\sqrt{k}}-r}(q)})$ because that would increase the diameter. \square

Open problem: If (M^n, g) has $\text{Ric} \geq (n-1)k > 0$ and $\text{Vol}(M, g) > \frac{1}{2} \text{Vol}(S^n(1/\sqrt{k}))$, then $M \underset{\text{homeo?}}{\cong} S^n$.

Exercise: a) Find counter-example with $\text{Vol}(M, g) = \frac{1}{2} \text{Vol}(S^n(1/\sqrt{k}))$.

↖ HWS

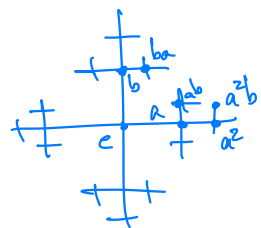
b) Prove that (M^n, g) as above is simply-connected.

Hint: if M is not simply connected, take its universal covering.

Lecture 23 5/1/2024

A quick taste of Geometric Group Theory:

- If Γ is finitely generated, fix a finite generating set G , with $e \in G$ and $G^{-1} = G$. Then define growth function for Γ :



Cayley graph of $F = \langle a, b \rangle$

$$N_k^G = \# \{ g \in \Gamma : g = g_1 \cdots g_k, \text{ with } g_i \in G \}$$

↖ # of group elements that can be written as product of k generators in the fixed generating set G .

↖ In terms of the Cayley graph with the word metric, this is the cardinality of the closed ball of radius k around $e \in \Gamma$

- If G' is another choice of generating set for Γ as above, then

$$N_k^{G'} \geq N_{Ck}^G \text{ and } N_k^G \geq N_{Dk}^{G'} \text{ for some constants } C, D > 0,$$

so can ignore choice of gen. set G for questions below.

• Q: How does N_k grow with k ? Polynomially? Exponentially?

Thm (Milnor '68). If (M, g) is complete and has $\text{Ric} \geq 0$, then any finitely generated subgroup $\Gamma < \pi_1 M$ has $\underline{N_k \leq C \cdot k^n}$.

ie, "polynomial growth"

Pf: Choose $\sigma \in \tilde{M}^n$, and let $V(r) = \text{Vol}(B_r(\sigma))$. By Bishop Volume Comp,

$$V(r) \leq \text{Vol}(B_r^{\mathbb{R}^n}(\sigma)) = \frac{\pi^{n/2}}{\Gamma(\frac{n}{2}+1)} r^n. \text{ Let } G = \{g_1, \dots, g_p\} \text{ be the}$$

fixed generating set for $\Gamma < \pi_1 M$ and $\mu = \max_{1 \leq i \leq p} \text{dist}(\sigma, g_i \cdot \sigma)$.

Then $B_{\mu \cdot k}(\sigma)$ has at least N_k^G distinct points of the form $g \cdot \sigma$, with $g \in \Gamma$. Choose $\varepsilon > 0$ s.t.

$g \cdot B_\varepsilon(\sigma) \cap B_\varepsilon(\sigma) = \emptyset$ if $g \neq e$. Then $B_{\mu \cdot k + \varepsilon}(\sigma)$ has at least N_k^G disjoint subsets of the form $g \cdot B_\varepsilon(\sigma)$, so

$$N_k^G \cdot V(\varepsilon) = \text{Vol}\left(\bigsqcup_{\substack{g=g_1 \dots g_k \\ g_i \in G}} g \cdot B_\varepsilon(\sigma)\right) \leq V(\mu k + \varepsilon)$$

Thus $N_k^G \leq \frac{V(\mu k + \varepsilon)}{V(\varepsilon)} \stackrel{\text{Bishop}}{\leq} \frac{\tilde{C} (\mu k + \varepsilon)^n}{V(\varepsilon)} \leq C \cdot k^n$ □

(recall: M compact $\Rightarrow \pi_1 M$ is finitely generated)

Thm (Milnor '68). If (M, g) is a closed Riem. mfd with $\text{sec} < 0$, and $\pi_1 M = \langle G \rangle$, $|G| < \infty$, then $\underline{N_k^G \geq a^k}$ for some $a > 1$.

ie, "exponential growth"

Ex: Fundamental group of hyperbolic manifold Σ^n has exponential growth; thus, cannot be π_1 of mfd w/ $\text{Ric} \geq 0$.

So, cannot "improve" the above Thm to $\text{scal} > 0$, as $\Sigma_x^2 S^{n-2}(\varepsilon)$ has $\text{scal} > 0$ for $n \geq 4$ and $\varepsilon > 0$ suff. small, if Σ^2 is a hyperbolic surface.

Conjecture (Milnor, 1968). If (M^n, g) is complete and has $\text{Ric} \geq 0$, then $\pi_1 M$ is finitely generated.

- For $n=3$, it was proven by [Lin, 2013] and indep. [Pan, 2017].

← Inventiones paper, uses minimal surfaces

← Grelle paper, uses Cheeger-Colding theory and Ric ≥ 0 limit spaces

- In November 2023, a counter-example (M^7, g) with $\text{Ric} \geq 0$ and $\pi_1 M^7 = \mathbb{Q}/\mathbb{Z}$ was announced by Brue-Naber-Semola, using a sophisticated gluing method to produce a "smooth fractal structure".

One of the founding achievements of Geometric Group Theory is:

Thm (Gromov '81) A finitely generated group Γ has polynomial growth if and only if Γ is virtually nilpotent ($\exists N \triangleleft \Gamma$ nilpotent with $[\Gamma:N] < \infty$.)

So, if $\Gamma < \pi_1 M$ is fin. gen. and M has $\text{Ric} \geq 0$, then Γ is virtually nilpotent.

Conversely, if Γ is fin. gen. and virtually nilpotent, then $\Gamma = \pi_1 M$ for some

M with $\text{Ric} \geq 0$ (Wilking '2000) ← This paper also shows that if a counter-example M to Milnor's conjecture exists, then it has a covering space $\tilde{M} \rightarrow M$ with $\pi_1 \tilde{M}$ abelian and not fin. gen (e.g., $\pi_1 \tilde{M} = \mathbb{Q}/\mathbb{Z}$.)

Stronger results about $\pi_1 M$ can be proven with stronger curvature assumptions:

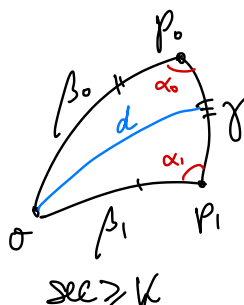
Toponogov Triangle Comparison

Here and throughout: if $K > 0$, then assume all lengths are $< \frac{\pi}{\sqrt{K}}$.

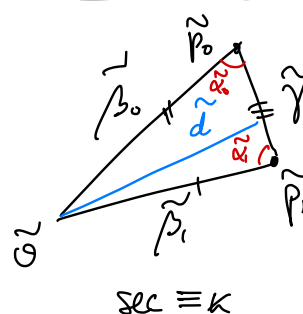
Triangle Version

If (M^n, g) has $\text{sec} \geq K$, $\sigma, p_0, p_1 \in M$,
 $\gamma: [0, L] \rightarrow M$ geod from p_0 to p_1 ,
 β_i min. geod from σ to p_i ,
 then $d = \text{dist}_g(\sigma, \gamma(t)) \geq \tilde{d} = \text{dist}_{\tilde{g}}(\tilde{\sigma}, \tilde{\gamma}(t))$
 for all $t \in [0, L]$ and $\alpha_i \geq \tilde{\alpha}_i$.

Original triangle

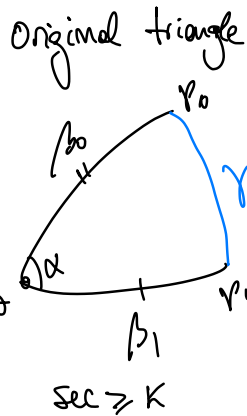


Comp. triangle w/ same side lengths

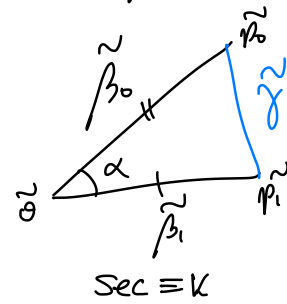


Hinge Version

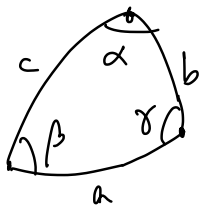
If (M^n, g) has $\sec \geq K$, $o, p_0, p_1 \in M$,
 β_i min. geod. from o to p_i ,
 Then $\ell(\gamma) \leq \ell(\tilde{\gamma})$; where $\gamma, \tilde{\gamma}$
 are the min. geod. that
 close the hinge: $\ell(\gamma) = \text{dist}_g(p_0, p_1)$
 $\ell(\tilde{\gamma}) = \text{dist}_{\tilde{g}}(\tilde{p}_0, \tilde{p}_1)$.



Comp. triangle w/ same
 hinge: $\ell(\beta_i) = \ell(\tilde{\beta}_i)$, $\alpha = \tilde{\alpha}$



Corollary: A geodesic triangle on a manifold with $\sec \geq 0$ satisfies



$$(i) \ell(c)^2 \leq \ell(a)^2 + \ell(b)^2 - 2\ell(a)\ell(b)\cos\gamma \quad \ell = \text{length}$$

$$(ii) \alpha + \beta + \gamma \geq \pi \quad \text{If } \sec > 0, \text{ then get strict inequalities.}$$

Pf: (i) is immediate:

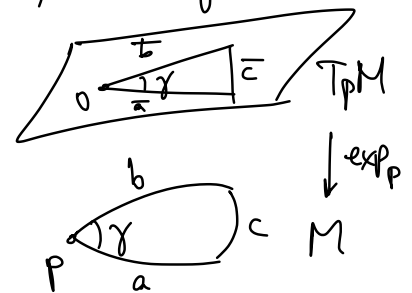
Gauss Lemma

$$\ell(a)^2 + \ell(b)^2 - 2\ell(a)\ell(b)\cos\gamma \stackrel{\downarrow}{=} \ell(\bar{a})^2 + \ell(\bar{b})^2 - 2\ell(\bar{a})\ell(\bar{b})\cos\gamma$$

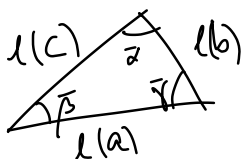
$$\stackrel{\text{Law of Cosines in } \mathbb{R}^2}{=} \ell(\bar{c})^2$$

$$\stackrel{\text{Toponogov (Hinge)}}{\geq} \ell(c)^2$$

where $a = \exp_p \bar{a}$, $b = \exp_p \bar{b}$, $c = \exp_p \bar{c}$.



(ii) Follows from (i) as in the $\sec \leq 0$ case: build comparison triangle in \mathbb{R}^2 with side lengths $\ell(a)$, $\ell(b)$, $\ell(c)$, and angles $\bar{\alpha}, \bar{\beta}, \bar{\gamma}$. Then $\ell(a)^2 + \ell(b)^2 - 2\ell(a)\ell(b)\cos\gamma \geq \ell(c)^2$



so $\cos\gamma \leq \cos\bar{\gamma}$ hence

$\gamma \geq \bar{\gamma}$. Similarly for α, β and get

$$\alpha + \beta + \gamma \geq \bar{\alpha} + \bar{\beta} + \bar{\gamma} = \pi.$$

□

Combining above w/
 earlier work on $\sec \leq 0$

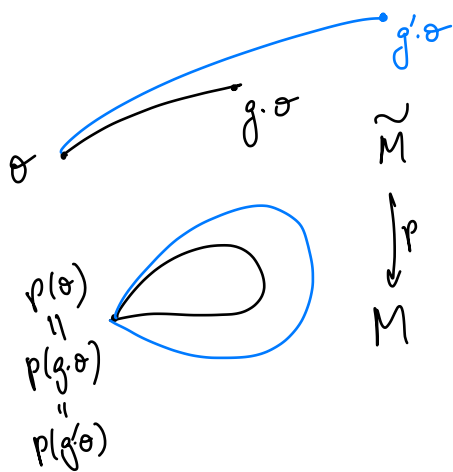
Cor: (M^n, g) has $\sec \geq 0$ (≤ 0) iff $\forall p \in M$, $\exp_p: C_p \subset T_p M \xrightarrow{\cong} M$
 is distance non-increasing (non-decreasing).

As before...

Thm (Gromov 1978). If (M^n, g) has $\sec \geq 0$, then $\pi_1 M$ can be generated by $\leq \sqrt{2n\pi} \cdot 2^{n-2}$ elements. If (M^n, g) has $\sec \geq -K^2$ and $\text{diam}(M) \leq D$, then $\pi_1 M$ can be generated by $\leq \frac{1}{2} \sqrt{2n\pi} (2 + 2 \cosh(2KD))^{\frac{n-1}{2}}$. ← Note: If $K \rightarrow 0$, then this becomes $\sqrt{2n\pi} \cdot 2^{n-2}$.

Pf: (Case $K=0$). Fix $\sigma \in \tilde{M}$ and consider the isometric action of $\Gamma = \pi_1 M$, by deck transformations. Define displacement of $g \in \Gamma$: $|g| = \text{dist}(\sigma, g \cdot \sigma)$.

Clearly, a min. geod. from σ to $g \cdot \sigma$ in \tilde{M} projects to geodesic loop based at $p(\sigma) \in M$, which has minimal length in its homotopy class. For any given $R > 0$, there are only finitely many $g \in \Gamma$ with $|g| \leq R$, because otherwise an infinite seq. $g_i \in \Gamma$ with $|g_i| \leq R$ would produce an infinite seq. $g_i \cdot \sigma$ of points in $B_R(\sigma)$, which has a limit and contradicts the covering property.



Thus, we can define $g_1 \in \Gamma$ s.t. $|g_1| = \min_{g \in \Gamma} |g|$, and $g_2 \in \Gamma$ with $|g_2| = \min_{g \in \Gamma \setminus \langle g_1 \rangle} |g|$; inductively, define a sequence $g_1, g_2, \dots \in \Gamma$ of generators with $|g_1| \leq |g_2| \leq \dots$ and $|g_{i+1}| = \min_{g \in \Gamma \setminus \langle g_1, \dots, g_i \rangle} |g|$. (Keep adding elements g_i until a "short basis" set of generators is achieved!)

Set $l_{ij} = \text{dist}(g_i \cdot \sigma, g_j \cdot \sigma)$ for all $i < j$. Then $l_{ij} \geq |g_j|$,

for otherwise $\bar{g} = g_i^{-1} \cdot g_j$ would have

$$|\bar{g}| = l_{ij} < |g_j| \quad \text{and} \quad \langle g_1, \dots, g_i, \dots, g_j \rangle = \langle g_1, \dots, g_i, \dots, \bar{g} \rangle$$

hence contradict the min. choice of g_j above.

Note that all sides of the triangles $\sigma, g_i \cdot \sigma, g_j \cdot \sigma$ are min geodesics.

By Toponogov, applied to the triangle $g_i \cdot o, g_j \cdot o, o$,
we have that $\alpha_{ij} \geq \tilde{\alpha}_{ij}$.

Law of cosines in \mathbb{R}^2 :

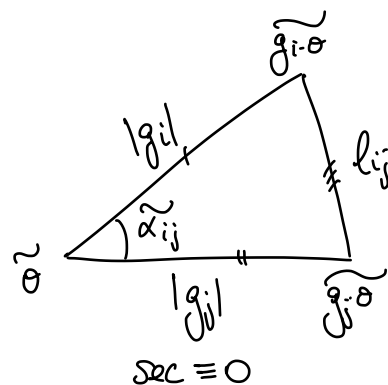
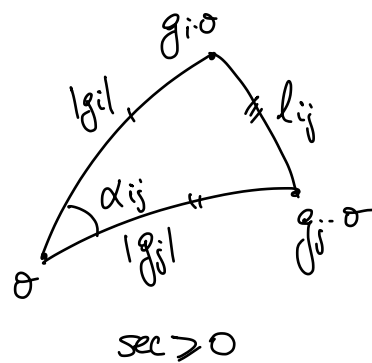
$$l_{ij}^2 = |g_i|^2 + |g_j|^2 - 2|g_i||g_j| \cos \tilde{\alpha}_{ij}$$

$$\Rightarrow \cos(\tilde{\alpha}_{ij}) = \frac{|g_i|^2 + |g_j|^2 - l_{ij}^2}{2|g_i||g_j|}$$

$$\leq \frac{|g_i|^2 + (|g_i|^2 - |g_j|^2)}{2 \cdot |g_i|^2} = \frac{1}{2}$$

$|g_i| = |g_j| = l_{ij} \text{ if } i < j$

$$\Rightarrow \alpha_{ij} \geq \tilde{\alpha}_{ij} \geq \frac{\pi}{3}$$




Let $v_i \in T_o \tilde{M}$ be the unit vector tangent to the min. geod. from o to $g_i \cdot o$. By the above, the distance (on the unit sphere in $T_o \tilde{M}$) between v_i and v_j is $\alpha_{ij} \geq \frac{\pi}{3}$, so the balls of radius $\frac{\pi}{6}$ centered at v_i and v_j must be disjoint. (This already proves there can be only finitely many v_i 's, hence finitely many g_i 's so $\Gamma = \pi_1 M$ is finitely generated.) Moreover, as $|g_i^{-1}| = |g_i|$, we must also have that distance from $-v_i$ to v_j is $\geq \frac{\pi}{3}$ if $i < j$, therefore the number of v_i 's is:

$$\#\{g_i\} = \#\{v_i\} \leq \frac{\text{Vol}(\mathbb{RP}^{n-1}(1))}{\text{Vol}(B_{\pi/6}^{S^{n-1}}(v))}$$

\leftarrow Volume of the set of $\pm v \in S^{n-1} \subset T_o \tilde{M}$.
 \leftarrow Volume of each disjoint ball around $\pm v_i \in S^{n-1}$.

Standard computations give:

Volume of spherical ball of radius r is \geq volume of Euclidean ball of radius $\sin r$. ($0 < r < \pi/2$) 

$$\text{Vol}(B_{\pi/6}^{S^{n-1}}(v)) \geq \text{Vol}(B_{\sin \pi/6}^{\mathbb{R}^{n-1}}(0)) = \frac{\pi^{\frac{n-1}{2}}}{\Gamma(\frac{n+1}{2})} 2^{n-1}$$

(Γ = Gamma function)

log-concavity of Γ :

$$\frac{\Gamma(\frac{n+1}{2})}{\Gamma(\frac{n}{2})} \leq \sqrt{\frac{n}{2}}$$

$$\text{Vol}(\mathbb{RP}^{n-1}(1)) = \frac{1}{2} \text{Vol}(S^{n-1}(1)) = \frac{\pi^{n/2}}{\Gamma(\frac{n}{2})}$$

$$\text{So } \#\{g_i\} = \#\{v_i\} \leq \frac{\pi^{n/2} \Gamma(\frac{n+1}{2}) 2^{n-1}}{\Gamma(\frac{n}{2}) \cdot \pi^{\frac{n-1}{2}}} = \sqrt{\pi} \frac{\Gamma(\frac{n+1}{2})}{\Gamma(\frac{n}{2})} 2^{n-1} \leq \sqrt{2n\pi} \cdot 2^{n-2}$$

For case $\text{sec} \geq -k^2$, see Eschenburg's notes. □

Using Bishop Volume Comparison, Toponogov Triangle Comparison, Critical point theory for distance functions and topological constructions, Gromov proved the following:

Thm (Gromov '1981).

i) If (M^n, g) is a complete mfd with $\text{sec} \geq 0$, then $\sum_{k=0}^n b_k(M) \leq C(n)$.

ii) If (M^n, g) is a closed mfd with $\text{sec} \geq -k^2$ and $\text{diam} \leq D$, then $\sum_{k=0}^n b_k(M) \leq C(n)^{1+kD}$.

Cannot replace the hypothesis $\text{sec} \geq 0$ to $\text{Ric} > 0$ because:

"Docking station" 

Thm (Sha-Yang '90s). $\forall l \in \mathbb{N}$, $\#^l S^2 \times S^2$ and $\#^k \mathbb{CP}^2 \#^l \mathbb{CP}^2$ have $\text{Ric} > 0$.

also $\#^l S^n \times S^m$ for any $n, m \geq 2$, $l \geq 1$.

Thm. (Perelman '97). $\forall l \in \mathbb{N}$, $\#^l \mathbb{CP}^2$ has a metric with $\text{Ric} > 0$, $\text{diam} = 1$ and $\text{Vol} \geq V > 0$.

Thus, since $b_2(\#^l S^2 \times S^2) = 2l$ and $b_2(\#^k \mathbb{CP}^2 \#^l \mathbb{CP}^2) = k+l$, only finitely many of these manifolds can have $\text{sec} \geq 0$. Currently,

- only S^4 and \mathbb{CP}^2 are known to have $\text{sec} > 0$ and

- only $S^2 \times S^2$ and $\mathbb{CP}^2 \# \pm \mathbb{CP}^2$ are known to have $\text{sec} \geq 0$.

Conjecturally, the above is the complete list of simply-connected 4-mflds with $\text{sec} > 0$ and $\text{sec} \geq 0$.

Note: $\text{scal} > 0$ is preserved by $\#$; indeed by surgeries of codimension ≥ 3 .

! Related open question: is there a simply-connected closed mfd that admits $\text{scal} > 0$ but does not admit $\text{Ric} > 0$?

(double disc: )

Note: As $l \rightarrow +\infty$, Perelman's $\#^l \mathbb{CP}^2$ converges to $B^4 \cup B^4$ flat

Lie Groups and Lie Algebras

Mostly taken from my book w/ Alexandrino:
 "Lie groups and geometric aspects of isometric actions"
 Chapters 1, 2.

Def. A manifold G is a Lie group if it is a group, and the maps

$$G \times G \ni (g, h) \mapsto gh \in G, \quad G \ni g \mapsto g^{-1} \in G$$

are smooth. Equivalently, the map $G \times G \ni (g, h) \mapsto g \cdot h^{-1} \in G$ is smooth.

Rmk: Equivalently, could define requiring only $(g, h) \mapsto gh$ is smooth; inversion is then also smooth by Inverse Function Theorem.

Ex: $(\mathbb{R}, +)$, (S^1, \cdot)

Examples (Classical Lie groups).

$$GL(n, F) = \{A \in M_{n \times n}(F) : \det A \neq 0\}, \quad F \in \{\mathbb{R}, \mathbb{C}, \mathbb{H}\}$$

$$SL(n, F) = \{A \in GL(n, F) : \det A = 1\}$$

$$O(n) = \{A \in GL(n, \mathbb{R}) : A^T A = Id\} \quad \text{orthogonal group}$$

$$SO(n) = O(n) \cap SL(n, \mathbb{R})$$

$$U(n) = \{A \in GL(n, \mathbb{C}) : A^* A = Id\} \quad \text{unitary group}$$

$$SU(n) = U(n) \cap SL(n, \mathbb{C})$$

$$Sp(n) = \{A \in GL(n, \mathbb{H}) : A^* A = Id\} \quad \text{symplectic group.}$$

Def. A vector space \mathfrak{g} is a Lie algebra if it is endowed with a bilinear skewsymmetric map $[\cdot, \cdot] : \mathfrak{g} \times \mathfrak{g} \rightarrow \mathfrak{g}$, s.t. $[[X, Y], Z] + [[Y, Z], X] + [[Z, X], Y] = 0$.
 (i.e., $[X, Y] = -[Y, X]$) $\forall X, Y, Z \in \mathfrak{g}$.

Ex. \mathbb{R}^n with $[\cdot, \cdot] \equiv 0$.

$$\mathfrak{gl}(n, F) = M_{n \times n}(F), \quad [A, B] = AB - BA$$

$$\mathfrak{sl}(n, F) = \{X \in \mathfrak{gl}(n, F) : \text{tr } X = 0\}$$

$$\mathfrak{o}(n) = \mathfrak{so}(n) = \{X \in \mathfrak{gl}(n, \mathbb{R}) : X^T + X = 0\}$$

$$\mathfrak{u}(n) = \{X \in \mathfrak{gl}(n, \mathbb{C}) : X^* + X = 0\}$$

$$\mathfrak{su}(n) = \mathfrak{u}(n) \cap \mathfrak{sl}(n, \mathbb{C})$$

$$\mathfrak{sp}(n) = \{X \in \mathfrak{gl}(n, \mathbb{H}) : X^* + X = 0\}$$

Def: Left translation $L_g: G \rightarrow G$, Right translation $R_g: G \rightarrow G$
 $x \mapsto g \cdot x$ $x \mapsto xg$

are both smooth and have smooth inverses $L_{g^{-1}}$ and $R_{g^{-1}}$, hence are diffeomorphisms.

Def. A tensor X over G , e.g., a vector field, k -form, etc, is called left-invariant if $dL_g X = X \circ L_g$, i.e. $X(gh) = d(L_g)_h X(h)$, and similarly right-invariant if $dR_g X = X \circ R_g$. If it is simultaneously left and right invariant, then it is called bi-invariant.

Prop. A left (or right) invariant tensor is smooth.

Pf. (Vector fields) $\mu: G \times G \rightarrow G$, $\mu(g, h) = g \cdot h$ is smooth, and so is $s: G \rightarrow TG \times TG$, $s(g) = (0_g, X(e))$, where $g \mapsto 0_g$ is the zero section of TG . Then $X = d\mu \circ s$ is a composition of smooth maps, hence smooth, and all left-invariant vector fields are of that form.

Def: A group homomorphism $\phi: G \rightarrow H$ is a Lie group homomorphism if it is smooth (actually, continuity \Rightarrow smoothness). A linear transf $\phi: \mathfrak{g} \rightarrow \mathfrak{h}$ is a Lie algebra homomorphism if $[\phi(X), \phi(Y)] = \phi([X, Y])$.

Prop. Given a Lie group G , let $\mathfrak{g} = \{X \in \mathfrak{X}(G): X \text{ left-invariant}\}$.

(i) \mathfrak{g} , endowed with Lie bracket of vector fields, is a Lie algebra.

(ii) Endow $T_e G$ with the Lie bracket $[X, Y] := [\tilde{X}, \tilde{Y}]_e$, where

usually written just like for simplicity $\tilde{X} = d(L_g)_e X$, $\tilde{Y} = d(L_g)_e Y$. Then $(T_e G, [\cdot, \cdot])$ is a Lie algebra, and the evaluation map $\text{eval}_e: \mathfrak{g} \rightarrow T_e G$ is a Lie algebra isomorphism.

Pf. (i) is straight forward from linearity of $d(L_g)_e$ and noticing X is left-invariant iff it is L_g -related to itself

(ii) eval_e is clearly linear and injective; if $X_e = Y_e$, then $X_g = dL_g X_e = dL_g Y_e = Y_g$, $\forall g$ so $X=Y$. It is also clearly surjective: given $v \in T_e G$, $X = dL_g v \in \mathfrak{g}$ has $X_e = v$. By its definition, it preserves brackets, so it is a Lie algebra isom. \square

Def. The Lie algebra of the Lie group G is the above $\mathfrak{g} = T_e G$.

Ex: If (M^n, g) is a complete Riem. mfd, then $G = \text{Isom}(M, g)$ is a Lie group (Myers-Steenrod) and its Lie algebra is the space of Killing vector fields $\mathfrak{g} = \{X \in \mathfrak{X}(M) : \nabla X \text{ skew symmetric}\}$.

Lie group $G \xrightarrow{\quad} \text{Lie algebra } \mathfrak{g}$
← converse?

Lie's Third Theorem. Let \mathfrak{g} be a (finite-dim.) Lie algebra. There exists a unique connected, simply-connected, Lie group G with Lie algebra isomorphic to \mathfrak{g} .

Def. A Lie subgroup $H < G$ is a subgroup which is an immersed submanifold and $H \times H \ni (x, y) \mapsto xy^{-1} \in H$ is smooth.

Lemma. If $\varphi: G_1 \rightarrow G_2$ is a Lie gp. homomorphism, given $X \in \mathfrak{g}_1$, there is a unique $Y \in \mathfrak{g}_2$ that is φ -related to X .

Pf. Define $Y = dL_g d\varphi_e X_e$. Then:

$$\begin{aligned} d\varphi_g X_g &= d\varphi_g dL_g X_e = d(\varphi \circ L_g)_e X_e \\ &= d(L_{\varphi(g)} \circ \varphi)_e X_e = dL_{\varphi(g)} d\varphi_e X_e = Y_{\varphi(g)} \end{aligned}$$

Uniqueness follows from left-invariance of Y .

Prop. If $\varphi: G_1 \rightarrow G_2$ is a Lie gp homomorphism, then $d\varphi: \mathfrak{g}_1 \rightarrow \mathfrak{g}_2$ is a Lie alg. homomorphism.

Pf. $X_1, X_2 \in \mathfrak{g}_1 \xrightarrow{\text{Lemma}} Y_1, Y_2 \in \mathfrak{g}_2$ are the left-inv. extensions of $d\varphi_e X_1, d\varphi_e X_2$, so, since Lie brackets of φ -related vector fields are φ -related,

$$Y_i \circ \varphi = d\varphi_e X_i \Rightarrow [d\varphi_e X_1, d\varphi_e X_2]_e = [Y_1, Y_2]_e = d\varphi_e([X_1, X_2]).$$

Cor. If $H < G$ is a Lie subgroup, $i: H \hookrightarrow G$ is an injective Lie gp. homomorphism that induces an isomorphism $d i_e$ from the Lie algebra \mathfrak{h} of H and the Lie subalgebra $d i_e(\mathfrak{h})$ of \mathfrak{g} . □

Thm. Let G be a Lie group with Lie algebra \mathfrak{g} , and $\mathfrak{h} < \mathfrak{g}$ a Lie subalgebra. Then there exists a unique connected Lie subgroup $H < G$ with Lie algebra \mathfrak{h} .

Pf. The distribution $D_{\mathfrak{h}} = \{X_{\mathfrak{h}} = dL_g X \text{ for } X \in \mathfrak{h}\}$ of G is involutive b/c \mathfrak{h} is a Lie algebra. By Frobenius, it is integrable; let H be the leaf through $e \in G$. Since D is left-invariant, L_g maps leaves to leaves, so $L_{h^{-1}}(H) = H$ for all $h \in H$, i.e., H is a subgroup. □

Uniqueness follows from:

Lemma: Let $G_0 < G$ be the connected component of $e \in G$. Then $G_0 < G$ and connected components of G are of the form $g \cdot G_0$ for some $g \in G$. Moreover, $\forall U \ni e$ open neighborhood, $G_0 = \bigcup_{n \in \mathbb{N}} \{g_1^{\pm 1} \dots g_n^{\pm 1} : g_i \in U\}$.

Pf. See my book w/ Alexandrino.

Thm. If G is a connected Lie gp, there is a unique simply connected Lie group \tilde{G} and a Lie gp homomorphism $\pi: \tilde{G} \rightarrow G$ which is a covering map.

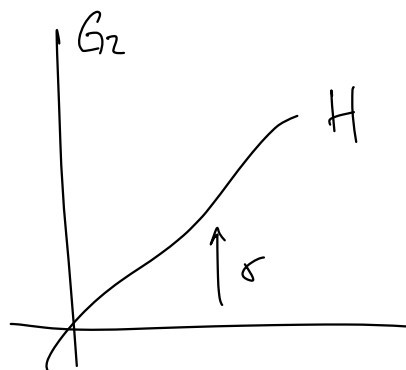
E.g., $\mathbb{R}^n \rightarrow T^n$, $SU(2) \rightarrow SO(3)$, $SU(2) \times SU(2) \rightarrow SO(4)$
 $Sp(2) \rightarrow SO(5)$, $SU(4) \rightarrow SO(6)$

Prop. A Lie gp homomorphism $\pi: G_1 \rightarrow G_2$ between connected groups is a covering map $\iff d\pi_e: \mathfrak{g}_1 \rightarrow \mathfrak{g}_2$ is an isomorphism.

Pf. A covering map is a local diffeo, so \Rightarrow is clear.
 Conversely, if $d\pi_e$ is an isom., by Inv. Funct. Thm., $\exists U \subset G_1$ and $V \subset G_2$ neighborhoods of the identity, s.t. $\pi|_U: U \rightarrow V$ is a diffeo. By Lemma, given $h \in G_2$, $h = h_1^{\pm 1} \dots h_n^{\pm 1}$ w/ $h_i \in V$, and $\exists g_i \in U$ s.t. $\pi(g_i) = h_i$ so $\pi(g_1^{\pm 1} \dots g_n^{\pm 1}) = h_1^{\pm 1} \dots h_n^{\pm 1} = h$, so π is a surjective homomorphism. One then easily checks it is a covering map with deck transf. gp. $\ker \pi$. \square

Lemma. If $\varphi, \psi: G_1 \rightarrow G_2$ are Lie gp homomorphisms, G_1 connected, and $\theta: \mathfrak{g}_1 \rightarrow \mathfrak{g}_2$ a Lie algebra homomorphism, $d\varphi_e = d\psi_e = \theta$, then $\varphi = \psi$.

Pf. Consider the graph of θ , $\mathfrak{h} := \{(X, \theta(X)) : X \in \mathfrak{g}_1\}$, which is a Lie subalgebra of $\mathfrak{g}_1 \oplus \mathfrak{g}_2$. By a Theorem above, there exists a unique connected Lie subgroup H of $G_1 \times G_2$ with Lie algebra \mathfrak{h} .



$$\text{then } \sigma: G_1 \longrightarrow G_1 \times G_2$$

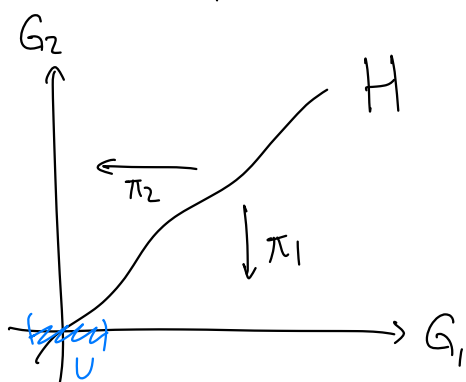
$$g \longmapsto (g, \varphi(g))$$

is a Lie grp. homom. with $d\sigma(X) = (X, \theta(X))$,
 a Lie alg. homom., and $\sigma(G_1) \subset G_1 \times G_2$

Lie subgroup with Lie algebra \mathfrak{h} . By uniqueness, $\sigma(G_1) = H$.
 So replacing φ with φ' , if $d\varphi_e = d\varphi'_e = \theta$, we would obtain
 the same subgroup of $G_1 \times G_2$, which is the graph of the
 homomorphism $\varphi = \varphi'$. □

Thm. If $\theta: \mathfrak{g}_1 \rightarrow \mathfrak{g}_2$ is a Lie algebra homomorphism, and G_1
 is connected and simply connected, then $\exists \varphi: G_1 \rightarrow G_2$ unique
 Lie group homomorphism w/ $d\varphi_e = \theta$. This uniqueness is crucial in what follows; later references to "uniqueness" point here.

Pf. Let $\gamma = \text{graph } \theta$ and $H \subset G_1 \times G_2$ its Lie group, as above.



Then $(\pi_1, \text{id}): H \rightarrow G_1$ is a Lie gp
 homomorphism, $d(\pi_1, \text{id})_e(X, \theta(X)) = X$, so
 it is locally invertible near the identity:
 $(\pi_1, \text{id})^{-1}: \underset{G_1}{U} \rightarrow \underset{H}{V}$ is a diffeo.

Let $\varphi = \pi_2 \circ (\pi_1, \text{id})^{-1}: U \rightarrow G_2$. Then φ is a local homomorphism
 with $d\varphi_e = \theta$, since

$$d\varphi_e X = d(\pi_2 \circ (\pi_1, \text{id})^{-1})_e X = d\pi_2 (d(\pi_1, \text{id})^{-1} X)$$

$$= d\pi_2 (X, \theta(X)) = \theta(X).$$

Since $d(\pi, \circ i)$ is an isom., $(\pi, \circ i): H \rightarrow G_1$ is a covering map. As G_1 is simply-connected, $\pi, \circ i$ is a diffeomorphism so can be globally inverted, hence $\varphi: G_1 \rightarrow G_2$ can be globally defined as $\varphi = \pi_2 \circ (\pi, \circ i)^{-1}$. Uniqueness follows from Lemma. \square

Cor. G_1, G_2 connected, simply-connected, $\theta: \mathfrak{g}_1 \rightarrow \mathfrak{g}_2$ isomorphism then $\exists! \varphi: G_1 \rightarrow G_2$ isomorphism st $d\varphi_e = \theta$; i.e. Lie groups G_1 and G_2 as above are isomorphic if and only if their Lie algebras are isomorphic.

Def. A Lie group homomorphism $\lambda: \mathbb{R} \rightarrow G$ is called a 1-parameter subgroup of G .

By the above theorems, the Lie algebra homomorphism $\theta: \mathbb{R} \rightarrow \mathfrak{g}$, $\theta(t) = tX$ (for some fixed $X \in \mathfrak{g}$) "integrates" to a unique 1-param. subgroup $\lambda_X: \mathbb{R} \rightarrow G$ s.t. $\lambda'_X(0) = X$, which is also the integral curve through $e \in G$ of the left-invariant vector field X :

$$\lambda'_X(t) = \frac{d}{ds} \lambda_X(t+s) \Big|_{s=0} = dL_{\lambda_X(t)} \lambda'_X(0) = dL_{\lambda_X(t)} X = X_{\lambda_X(t)}$$

Def. The (Lie) exponential of the Lie group G is

$$\exp: \mathfrak{g} \rightarrow G, \quad \exp(X) = \lambda_X(1)$$

Rmk: If $G < GL(n, F)$ is a matrix Lie group, then $\exp: \mathfrak{g} \rightarrow G$ coincides with matrix exponentiation $\exp X = e^X = \sum_{k=0}^{+\infty} \frac{X^k}{k!}$. 29

Recap last lecture.

Prop: $\exp: \mathfrak{g} \rightarrow G$ satisfies the following properties

- (i) $\exp(tX) = \lambda_X(t)$
- (ii) $\exp(-tX) = \exp(tX)^{-1}$
- (iii) $\exp(t_1X + t_2X) = \exp t_1X \cdot \exp t_2X$
- (iv) $\exp: T_e G \rightarrow G$ is smooth and $d(\exp)_0 = \text{id}$; hence \exp is a local diffeo from neighborhood of $0 \in T_e G$ to neighborhood of $e \in G$.

Pf. Let $\lambda(s) = \lambda_X(st)$. Differentiating at $s=0$, we have

$$\lambda'(0) = \frac{d}{ds} \lambda_X(st) \Big|_{s=0} = \lambda'_X(0)t = tX.$$

Thus, by uniqueness of the 1-param. subgroup with initial velocity tX , we have $\lambda_X(st) = \lambda_{tX}(s)$. Setting $s=1$ we obtain (i). Since $\lambda_X: \mathbb{R} \rightarrow G$ is a Lie group homomorphism, (ii), (iii) follow. See book for pf of (iv), similar to Riccati case.

Prop. The exponential map $\exp: \mathfrak{gl}(n, F) \rightarrow GL(n, F)$ coincides with matrix exponentiation $\exp X = e^X = \sum_{k=0}^{+\infty} \frac{X^k}{k!}$.

Pf. The series $e^X = \sum_{k=0}^{+\infty} \frac{X^k}{k!}$ converges uniformly in compacts of $\mathfrak{gl}(n, F)$, and $[X, Y] = 0$ if and only if $e^{X+Y} = e^X \cdot e^Y$. Let $\lambda: \mathfrak{gl}(n, F) \rightarrow GL(n, F)$, $\lambda(t) = e^{tX}$. Each entry in the matrix e^{tX} is a power series with infinite radius of convergence, so λ is smooth. Differentiating term-by-term, $\lambda'(0) = X$. Since λ is a 1-parameter subgroup of $GL(n, F)$, by uniqueness it follows that $\lambda(t) = \exp tX$. □

Prop. If $\varphi: G_1 \rightarrow G_2$ is a Lie gp homomorphism, then

$$\begin{array}{ccc} \mathfrak{g}_1 & \xrightarrow{d\varphi} & \mathfrak{g}_2 \\ \exp^1 \downarrow & & \downarrow \exp^2 \\ G_1 & \xrightarrow{\varphi} & G_2 \end{array} \quad \text{commutes.}$$

Pf. $\alpha(t) = \varphi(\exp^1(tX))$ and $\beta(t) = \exp^2(d\varphi_e tX)$ are 1-param. subgps of G_2 and $\alpha'(0) = \beta'(0) = d\varphi_e X$, so $\alpha = \beta$ by uniqueness.

Cor. If $H < G$, then $i \circ \exp^H = \exp^G \circ d i_e$ where $i: H \hookrightarrow G$ is inclusion.

Campbell - Baker - Hausdorff formulas:

$$\exp(tX) \exp(tY) = \exp\left(t(X+Y) + \frac{t^2}{2}[X,Y] + O(t^3)\right)$$

$$\exp(tX) \exp(tY) \exp(-tX) = \exp\left(tY + t^2[X,Y] + O(t^3)\right)$$

Pf. See Frivak vol 1.

Def. A representation of a group G on a vector space V is a group homomorphism $\varphi: G \rightarrow \text{Aut}(V)$.

Def. The adjoint representation Ad of a Lie group G on its Lie algebra \mathfrak{g} is $\text{Ad}: G \rightarrow \text{Aut}(\mathfrak{g})$, $\text{Ad}(g)X = d(a_g)_e X$, where $a_g: G \rightarrow G$ is conjugation by g , i.e., $a_g(x) = gxg^{-1}$.

By the Chain rule, we have $\text{Ad}(g) = d(L_g)_{g^{-1}} = d(R_{g^{-1}})_e$.

Note that

$$\text{Ad}(g)X = \frac{d}{dt} a_g(\exp tX) \Big|_{t=0} = \frac{d}{dt} g \exp(tX) g^{-1} \Big|_{t=0}$$

so, since \exp and Lie gp/alg. homomorphisms commute,

$$\exp(t \text{Ad}(g)X) = a_g(\exp tX) = g \cdot \exp tX g^{-1}$$

so, setting $t=1$, $\exp(\operatorname{Ad}(g)X) = g \cdot \exp X \cdot g^{-1}$

Differentiating again, we have: $\operatorname{ad}(X) : \mathfrak{g} \rightarrow \mathfrak{g}$, $\operatorname{ad}(X)Y = d\operatorname{Ad}_e(X)Y$
 which is a Lie algebra representation $\operatorname{ad} : \mathfrak{g} \rightarrow \operatorname{End}(\mathfrak{g})$.

By the Chain Rule,

$$\operatorname{ad}(X)Y = \left. \frac{d}{dt} \operatorname{Ad}(\exp tX)Y \right|_{t=0}$$

Since \exp and Lie gr/alg. homomorphisms commute,

$$\operatorname{Ad}(\exp(tX)) = \exp(t\operatorname{ad}(X))$$

so, setting $t=1$, we see that the following diagram commutes

$$\begin{array}{ccc} \mathfrak{g} & \xrightarrow{\operatorname{ad}} & \operatorname{End}(\mathfrak{g}) \\ \exp \downarrow & & \downarrow \exp \\ G & \xrightarrow{\operatorname{Ad}} & \operatorname{Aut}(\mathfrak{g}) \end{array}$$

note $\operatorname{Aut}(\mathfrak{g}) \subset GL(\mathfrak{g})$ is the closed subgroup given by isomorphisms which are Lie algebra isomorphisms (i.e., preserve the bracket), thus it is a Lie subgroup of $GL(\mathfrak{g})$, with Lie algebra $\operatorname{End}(\mathfrak{g})$.

Prop. $\operatorname{ad}(X)Y = [X, Y]$.

Pf. By CBH formulas, $\exp(tX) \exp(tY) \exp(-tX) = \exp(tY + t^2[X, Y] + O(t^3))$,
 so with $g = \exp(tX)$,

$$\exp(\operatorname{Ad}(g)tY) = g \cdot \exp(tY) \cdot g^{-1} = \exp(tY + t^2[X, Y] + O(t^3))$$

Since \exp is locally injective near $0 \in \mathfrak{g}$,

$$\operatorname{Ad}(g)tY = tY + t^2[X, Y] + O(t^3)$$

so dividing by t and differentiating at $t=0$, we have

$$\operatorname{ad}(X)Y = \left. \frac{d}{dt} \operatorname{Ad}(\exp tX)Y \right|_{t=0} = \left. \frac{d}{dt} Y + t[X, Y] + O(t^2) \right|_{t=0} = [X, Y]. \quad \square$$

Def. The center of a Lie gp G is $Z(G) = \{g \in G : ghg^{-1} = h, \forall h \in G\}$
 and the center of a Lie alg. \mathfrak{g} is $Z(\mathfrak{g}) = \{X \in \mathfrak{g} : [X, Y] = 0 \forall Y \in \mathfrak{g}\}$.

Prop: If G is connected, then $Z(G) = \text{Ker Ad}$ is a normal Lie subgroup of G , with Lie algebra $Z(\mathfrak{g}) = \text{Ker ad}$.

Pf. If $g \in Z(G)$, then $ag = id \Rightarrow \text{Ad}(g) = id$. Conversely, if $g \in \text{Ker Ad}$, then $g(\exp tX)g^{-1} = \exp(tX)$ for all $X \in \mathfrak{g}$, so g commutes with all elements in a neighborhood of $e \in G$, hence with all elements in $G_0 = G$. Since $Z(G) \triangleleft G$ is closed, it is an embedded Lie subgroup. Since $d(\text{Ad})_e = \text{ad}$, it follows that its Lie algebra is Ker ad . \square

Rmk: If $\pi: \hat{G} \rightarrow G$ is a covering of connected Lie gps, then $\text{Ker } \pi$ is a discrete subgroup of $Z(\hat{G})$.

Lecture 26 5/10/2024

Def. A Riem. metric $\langle \cdot, \cdot \rangle$ on a Lie group G is left-invariant if $L_g: G \rightarrow G$ is an isometry $\forall g \in G$, i.e. $\forall g, h \in G, \forall X, Y \in T_h G$,

$$\langle d(L_g)_h X, d(L_g)_h Y \rangle_{gh} = \langle X, Y \rangle_h$$

Similarly, it is right-invariant if $R_g: G \rightarrow G$ is an isometry $\forall g \in G$.
 Note that an inner product $\langle \cdot, \cdot \rangle_e$ on $T_e G$ defines a unique left-invariant metric on G : $\langle X, Y \rangle_g = \langle d(L_{g^{-1}})_g X, d(L_{g^{-1}})_g Y \rangle_e$

A metric on G is bi-invariant if it is left- and right-invariant.

Prop. Compact Lie groups admit bi-invariant metrics.

Pf. Let $\omega \in \Omega^n(G)$ be a right-invariant volume form, e.g., obtained by setting $\omega_g := R_g^{-*} \omega_e$, for a given volume form $\omega_e \in \wedge^n T_e G$; i.e., $\omega_g(X_1, \dots, X_n) = \omega_e(d(R_g^{-1})_g X_1, \dots, d(R_g^{-1})_g X_n)$. Let $\langle \cdot, \cdot \rangle$ be a right-invariant metric, e.g., $\langle X, Y \rangle_g = \langle d(R_g^{-1})_g X, d(R_g^{-1})_g Y \rangle_e$ for an arbitrary inner product $\langle \cdot, \cdot \rangle$ on $T_e G$. Define $\forall X, Y \in T_x G$

$$Q: T_x G \times T_x G \rightarrow \mathbb{R}, \quad Q(X, Y)_x = \int_G \langle dL_g X, dL_g Y \rangle_{gx} \omega.$$

Then Q is left-invariant because, setting $f(g) := \langle dL_g X, dL_g Y \rangle_{gx}$,

$$Q(dL_h X, dL_h Y)_{hx} = \int_G \langle dL_g dL_h X, dL_g dL_h Y \rangle_{ghx} \omega$$

$$= \int_G f(gh) \omega = \int_G R_h^* (f \omega) = \int_{R_h(G)} f \omega = Q(X, Y)_x$$

and Q is right-invariant because:

$$Q(dR_h X, dR_h Y)_{xh} = \int_G \langle dL_g dR_h X, dL_g dR_h Y \rangle_{g(xh)} \omega$$

$$= \int_G \langle dR_h dL_g X, dR_h dL_g Y \rangle_{(gx)h} \omega = \int_G \langle dL_g X, dL_g Y \rangle_{gx} \omega = Q(X, Y)_x$$

$R_h \circ L_g = L_g \circ R_h$
so also

$dR_h \circ dL_g = dL_g \circ dR_h$

Remark: Some noncompact Lie groups do not admit bi-invariant metrics, but some do (e.g. $\mathbb{R}^n \times G$). compact. □

Prop. The left-invariant metric $\langle \cdot, \cdot \rangle$ on G obtained from the inner product $\langle \cdot, \cdot \rangle_e$ on $T_e G$ is bi-invariant iff $\langle \text{Ad}(g)X, \text{Ad}(g)Y \rangle_e = \langle XY \rangle_e$ i.e., $\text{Ad}(g): \mathfrak{g} \rightarrow \mathfrak{g}$ is an isometry.

Pf. Exercise

Cor. $\left\{ \text{Bi-invariant metrics on } G \right\} \longleftrightarrow \left\{ \text{Ad-invariant inner products on } \mathfrak{g} \right\}$

Prop. Let Q be a bi-invariant metric on G , $X, Y, Z \in \mathfrak{g}$. Then

(i) $Q([X, Y], Z) = -Q(Y, [X, Z])$, i.e., $\text{ad}(X): \mathfrak{g} \rightarrow \mathfrak{g}$ is skew-symmetric.

(ii) $\nabla_X Y = \frac{1}{2} [X, Y]$

(iii) $R(X, Y)Z = \frac{1}{4} [Z, [X, Y]]$.

(iv) $Q(R(X \wedge Y), Z \wedge W) = \frac{1}{4} Q([X, Y], [Z, W])$

In particular, (G, Q) has $R \geq 0$ and hence $\text{sec} \geq 0$.

Pf. Differentiate $Q(\text{Ad}(\exp tX)Y, \text{Ad}(\exp tX)Z) = Q(Y, Z)$ at $t=0$:

$$Q(\text{ad}(X)Y, Z) + Q(Y, \text{ad}(X)Z) = 0$$

$$Q([X, Y], Z) + Q(Y, [X, Z]) = 0.$$

To compute the Levi-Civita connection, use Koszul formula: X, Y, Z are left-invariant.

$$\begin{aligned} Q(\nabla_Y X, Z) &= \frac{1}{2} \left(X(Q(Y, Z)) + Y(Q(X, Z)) - Z(Q(X, Y)) \right. \\ &\quad \left. - Q([X, Z], Y) - Q([Y, Z], X) - Q([X, Y], Z) \right) \\ &= \frac{1}{2} Q([Y, X], Z) + \frac{1}{2} \underbrace{(Q(\text{ad}(Z)X, Y) + Q(X, \text{ad}(Z)Y))}_{=0} \end{aligned}$$

i.e. $\nabla_Y X = \frac{1}{2} [Y, X]$; so $\nabla_X Y = \frac{1}{2} [X, Y]$. Then

$$\begin{aligned} R(X, Y)Z &= \nabla_X \nabla_Y Z - \nabla_Y \nabla_X Z - \nabla_{[X, Y]} Z \\ &= \frac{1}{4} [X, [Y, Z]] - \frac{1}{4} [Y, [X, Z]] - \frac{1}{2} [[X, Y], Z] \\ &= -\frac{1}{4} [[X, Y], Z] - \frac{1}{4} \underbrace{([[X, Y], Z] + [[Z, X], Y] + [[Y, Z], X])}_{=0 \text{ (Jacobi)}} \\ &= \frac{1}{4} [Z, [X, Y]]. \end{aligned}$$

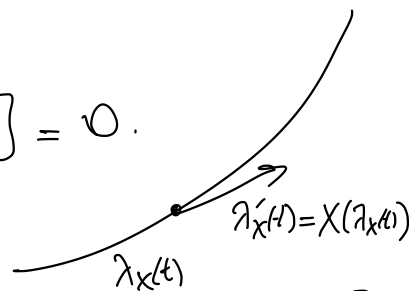
$$\begin{aligned} Q(R(X, Y), Z, W) &= Q(R(X, Y)W, Z) \\ &= \frac{1}{4} Q([W, [X, Y]], Z) \\ &= \frac{1}{4} Q([X, Y], [Z, W]). \end{aligned}$$

Rmk. If G is connected and $\langle \cdot, \cdot \rangle$ is a left-invariant metric on G s.t. $\langle \text{ad}(X)Y, Z \rangle = -\langle Y, \text{ad}(X)Z \rangle$, then $\langle \cdot, \cdot \rangle$ is bi-invariant.

Prop. $\exp: \mathfrak{g} \rightarrow G$ and $\exp_e: T_e G \rightarrow G$ agree on Lie groups with bi-invariant metric. In particular, \exp is surjective on compact connected Lie groups.

Pf. The 1-parameter subgroups $\gamma_X: \mathbb{R} \rightarrow G$ are geodesics, since $\gamma_X(t) = \exp(tX)$ are integral curves of X and hence

$$\frac{D}{dt} \gamma'_X(t) = \frac{D}{dt} X(\gamma_X(t)) = \nabla_{\gamma'_X(t)} X = \nabla_X X = \frac{1}{2} [X, X] = 0.$$



Conversely, the geodesic $\gamma: (-\varepsilon, \varepsilon) \rightarrow G$ with $\gamma(0) = e$, $\gamma'(0) = X$ is $\gamma(t) = \exp(tX)$, so can be extended to $\gamma: \mathbb{R} \rightarrow G$. Thus, \exp and \exp_e coincide.

If G is a compact Lie gp, then it has a bi-invariant metric, and $\exp_e = \exp$, so $\exp_e: T_e G \rightarrow G$ is globally defined b/c $\exp: \mathfrak{g} \rightarrow G$ is, hence G is complete by Hopf-Rinow.

Thus, $\exp_e: T_e G \rightarrow G$ is surjective, so $\exp: \mathfrak{g} \rightarrow G$ is surjective. \square

Rmk. $\exp: \mathfrak{sl}(2, \mathbb{R}) \rightarrow SL(2, \mathbb{R})$ is not surjective, so $SL(2, \mathbb{R})$ does not admit a bi-invariant metric.

Def The Killing form of \mathfrak{g} is $B: \mathfrak{g} \times \mathfrak{g} \rightarrow \mathbb{R}$ given by

$$B(X, Y) = \text{tr}(\text{ad}(X) \circ \text{ad}(Y)). \quad \leftarrow \text{symmetric b/c } \text{tr} AB = \text{tr} BA.$$

The Lie group is called semisimple if B is nondegenerate.

Prop. B is Ad-invariant

Pf If $\varphi: \mathfrak{g} \rightarrow \mathfrak{g}$ is a Lie algebra automorphism, then

$$\text{ad}(\varphi(X)) \varphi(Y) = [\varphi(X), \varphi(Y)] = \varphi([X, Y]) = (\varphi \circ \text{ad}(X))(Y)$$

$$\text{so } \text{ad}(\varphi(X)) = \varphi \circ \text{ad}(X) \circ \varphi^{-1} \quad \text{Thus,}$$

$$\begin{aligned} B(\varphi(X), \varphi(Y)) &= \text{tr}(\text{ad}(\varphi(X)) \circ \text{ad}(\varphi(Y))) \\ &= \text{tr}(\varphi \text{ad} X \varphi^{-1} \varphi \text{ad} Y \varphi^{-1}) \\ &= \text{tr}(\text{ad} X \text{ad} Y) = B(X, Y). \end{aligned}$$

Apply the above to $\varphi = \text{Ad}(g)$. \square

E.g., on $SU(n)$,

$$B(X, Y) = -2n \underbrace{\text{Re tr}(XY^*)}_{Q(X, Y) \text{ bi-inv. metric on } SU(n)}$$

on $O(n)$,

$$B(X, Y) = -(n-2) \underbrace{\text{tr} XY^T}_{Q(X, Y) \text{ bi-inv. metric on } SO(n)}$$

Cor. Let G be a semisimple Lie gp. with negative-definite Killing form. Then $-B$ is a bi-invariant metric.

Rmk. The Ricci tensor of a Lie group G with a bi-invariant metric is $\text{Ric}(X, Y) = \text{tr } R(\cdot, X)Y = \text{tr } \frac{1}{4}[Y, [\cdot, X]] = -\frac{1}{4}B(X, Y)$.

Thm. A semisimple connected Lie gp. is compact iff $B < 0$.

Pf. If $B < 0$, then $-B > 0$ is a bi-invariant metric on G . As \exp and \exp_e agree, by Hopf-Rinow, $(G, -B)$ is a complete Riem. mfd with $\text{Ric}(X, Y) = -\frac{1}{4}B(X, Y)$, i.e., $\text{Ric} \geq \frac{1}{4}(-B) > 0$. Thus, by Myers Theorem, G is compact (and $\pi_1 G$ is finite).

Conversely, if G is compact, then it admits a bi-invariant metric Q . Thus, if $\{e_i, \dots, e_n\}$ is an o.n.b. of \mathfrak{g} ,

$$\begin{aligned} B(X, X) &= \sum_{i=1}^n Q(\text{ad}(X)\text{ad}(X)e_i, e_i) \\ &= - \sum_{i=1}^n Q(\text{ad}(X)e_i, \text{ad}(X)e_i) \leq 0 \end{aligned}$$

If $\|\text{ad}(X)e_i\|^2 = 0$ for some $X \in \mathfrak{g}$, $X \neq 0$, then $B(Y, X) = 0$ for all $Y \in \mathfrak{g}$, so $\text{Ker } B \neq \{0\}$ contradicting the assumption that G is semisimple. Thus, $B < 0$. \square

Cor. If G is a semisimple connected compact Lie group, then $(G, -B)$ is an Einstein manifold with Einstein constant $\frac{1}{4}$.

Rmk. \mathfrak{g} is semisimple iff $\mathfrak{g} = \mathfrak{g}_1 \oplus \dots \oplus \mathfrak{g}_k$, where $\mathfrak{g}_i \triangleleft \mathfrak{g}$ are simple Lie algebras, i.e., noncommutative simple ideals of \mathfrak{g} .

Thm. If \mathfrak{g} has a bi-invariant metric Q , then $\mathfrak{g} = \mathfrak{g}_1 \oplus \dots \oplus \mathfrak{g}_k$ is the orthogonal direct sum of simple ideals (some may be Abelian).

The connected simply-connected Lie gp \tilde{G} with Lie algebra \mathfrak{g} is the product of normal Lie subgroups $\tilde{G} = G_1 \times \dots \times G_k$, s.t. $G_i = \mathbb{R}$ if \mathfrak{g}_i is Abelian, and G_i is compact if \mathfrak{g}_i is not Abelian.

Pf. See book.

Cor. If \mathfrak{g} has a bi-invariant metric, then $\mathfrak{g} \cong \mathcal{Z}(\mathfrak{g}) \oplus \underbrace{[\mathfrak{g}, \mathfrak{g}]}_{\text{"semisimple part"}}$.

Cor (Weyl). If G is a compact Lie gp. with finite center, then $\pi_1 G$ is finite and hence every Lie gp. with Lie algebra \mathfrak{g} is compact.

Pf. G compact $\Rightarrow \mathfrak{g}$ has bi-inv. metric. $\left. \begin{array}{l} |Z(G)| < \infty \Rightarrow Z(\mathfrak{g}) = \{0\} \end{array} \right\} \Rightarrow \mathfrak{g} \text{ is semisimple.}$
 \Downarrow
 $-B > 0$

$(G, -B)$ is Einstein w/ $\text{Ric} \geq \frac{1}{4}$, so $|\pi_1 G| < +\infty$ by Myers.

Thus, \tilde{G} is compact, and any Lie gp. with Lie algebra \mathfrak{g} is a quotient of \tilde{G} , hence also compact. \square

By the above, the classification of compact Lie groups reduces to the classification of simple Lie groups. \leftarrow Killing + Élie Cartan.

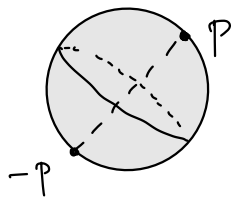
From last time: if G is a compact Lie gp, it admits a bi-inv. metric Q and (G, Q) has $R \geq 0$; in particular $\sec \geq 0$.

Homogeneous Spaces

Def: (M^n, g) is a homogeneous space if it has a transitive action by isometries: $\exists G < \text{Isom}(M^n, g)$ s.t. $G(p) = M$.

If $H = G_p = \{g \in G : g \cdot p = p\}$, then $M = G(p) = G/H$.

Ex: $S^n = \frac{O(n+1)}{O(n)} = \frac{SO(n+1)}{SO(n)}$, $\mathbb{RP}^n = \frac{SO(n+1)}{S(O(n) \times O(1))} \leftarrow = \left\{ A = \begin{pmatrix} A_1 & \\ & \pm 1 \end{pmatrix}; \begin{matrix} A_1 \in O(n) \\ \det A = 1 \end{matrix} \right\} \cong SO(n) \times \mathbb{Z}_2$



$O(n+1) \curvearrowright S^n \subset \mathbb{R}^{n+1}$
isotropy at $p \in S^n = O(n)$

$$\mathbb{CP}^n = \frac{U(n+1)}{U(n)U(1)} = \frac{SU(n+1)}{S(U(n)U(1))}$$

$U(n+1) \curvearrowright S^{2n+1} \subset \mathbb{C}^{n+1}$
(commutes w/ $U(1)$ action) \downarrow

$U(n+1) \curvearrowright \mathbb{CP}^n$

isotropy at $[e] \in \mathbb{CP}^n$: $U(n) \curvearrowright e^\perp \cong \mathbb{C}^n$
 $U(1) \curvearrowright e \cong \mathbb{C}$

$$\mathbb{HP}^n = \frac{Sp(n+1)}{Sp(n)}$$

$Sp(n+1) \curvearrowright S^{4n+3} \subset \mathbb{H}^{n+1}$
(commutes w/ $Sp(1)$) \downarrow
 $Sp(n+1) \curvearrowright \mathbb{HP}^n$

isotropy at $[e] \in \mathbb{HP}^n$: $Sp(n) \curvearrowright e^\perp \cong \mathbb{H}^n$
 $Sp(1) \curvearrowright e \cong \mathbb{C}$

$$\mathbb{CaP}^2 = \frac{F_4}{Spin(9)}$$

(The above comprise the compact rank one symmetric spaces "CROSS" for short)

Prop. If G is a cpct Lie gp, and $H < G$ have Lie algebras $\mathfrak{h} < \mathfrak{g}$, let $\mathfrak{m} = \mathfrak{h}^\perp$, so $\mathfrak{g} = \mathfrak{h} \oplus \mathfrak{m}$. Then $T_{eH} G/H \cong \mathfrak{m}$ and the isotropy representation $H \curvearrowright T_{eH} G/H$ is precisely $\text{Ad}: H \rightarrow \text{Aut}(\mathfrak{m})$.
so \mathfrak{m} is $\text{Ad}(H)$ -inv. $v \mapsto d\text{h}_{(eH)} v$

Cor. In the above situation: $\left\{ \begin{array}{c} G\text{-inv. metrics} \\ \text{on } G/H \end{array} \right\} \xleftrightarrow{1:1} \left\{ \begin{array}{c} \text{Ad}(H)\text{-inv. inner} \\ \text{products on } \mathfrak{m} \end{array} \right\}$

Def. The chosen bi-inv. metric Q on G is $\text{Ad}(H)$ -inv, hence induces a G -inv. metric on G/H , called normal homogeneous, and $G \rightarrow G/H$ is a Riem. submersion w/ totally geodesic fibers.

Prop. If $\pi: (M, g) \rightarrow (N, \check{g})$ is a Riem. submersion, then

$$\sec_Y(X \wedge Y) = \sec_{\check{g}}(\bar{X} \wedge \bar{Y}) + \frac{3}{4} \|[X, Y]^V\|^2$$

\bar{X} is the hor. lift of X , so $d\pi(\bar{X}) = X$, and $(\cdot)^V$ is the vertical component

In particular, if $\sec_{\check{g}} \geq 0$, then $\sec_Y \geq 0$.

Rmk: $\nabla_{\bar{X}} \bar{Y} = \overline{\nabla_X Y} + \frac{1}{2} [X, Y]^V$

Cor. Every compact homogeneous space admits metrics w/ $\sec \geq 0$.

Fact. The moduli space of G -inv. metrics w/ $\sec \geq 0$ on a cpt homog. space is path-connected. ← Essentially, it is star-shaped around a chosen normal hom. metric.

Ex: $S^{2n+1} \subset \mathbb{C}^{n+1}$ Let $V_Z = (iz_1, \dots, iz_{n+1})$ be the vertical direction.

\downarrow
 \mathbb{CP}^n

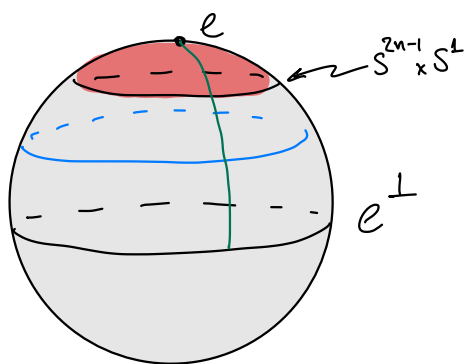
$$\begin{aligned} \left\langle \frac{1}{2} [\bar{X}, \bar{Y}], V \right\rangle &= \left\langle \nabla_{\bar{X}}^{S^{2n+1}} \bar{Y}, V \right\rangle = \left\langle \nabla_{\bar{X}}^{\mathbb{C}^{n+1}} \bar{Y}, V \right\rangle = \\ &= \bar{X} \underbrace{\langle \bar{Y}, V \rangle}_{=0} - \langle \bar{Y}, \nabla_{\bar{X}}^{\mathbb{C}^{n+1}} V \rangle = \langle \bar{Y}, \nabla_{i\bar{X}}^{\mathbb{C}^{n+1}} iV \rangle \\ &= \Pi^{S^{2n+1}}(\bar{Y}, i\bar{X}) = \langle \bar{Y}, i\bar{X} \rangle. \end{aligned}$$

so $\frac{1}{2} [\bar{X}, \bar{Y}]^V = \langle \bar{Y}, i\bar{X} \rangle V$ and $\frac{1}{4} \|[X, Y]^V\|^2 = \langle \bar{Y}, i\bar{X} \rangle^2$, so

$\sec_{\mathbb{CP}^n}(X \wedge Y) = 1 + 3 \langle \bar{Y}, i\bar{X} \rangle^2$ for all $\{X, Y\}$ orthonormal.

In particular, $1 \leq \sec_{\mathbb{CP}^n} \leq 4$. One easily computes $\text{Ric}_{\mathbb{CP}^n} = (2n+2)g_{\mathbb{CP}^n}$.

S^{2n+1}



Recall $S^{2n+1} = [0, \pi/2] \times S^{2n-1} \times S^1$ ← can think of S^1 acting fiberwise...
 $g = dr^2 + \sin^2 r g_{S^{2n-1}} + \cos^2 r g_{S^1}$.

The projection $\pi: S^{2n+1} \rightarrow \mathbb{CP}^n$ is a Riem. submersion hence a submetry;

$$\pi(B_r(p)) = B_r(\pi(p))$$

and the boundary of these geod. balls are distance spheres. For $0 < r < \pi/2$,

$$g_{\mathbb{CP}^n} = dr^2 + \underbrace{\sin^2 r (g|_H + \cos^2 t g|_V)}_{g_r}$$

where $g_{S^{2n-1}} = g|_H + g|_V$ is the metric on S^{2n-1} ; and g_r is the submersion metric from the S^1 action on $S^{2n-1} \times S^1$. ("Cheeger deformation")

Note: These dist. spheres on \mathbb{CP}^n are orbits of an action by $SU(n)$ on $e^\perp \subset \mathbb{C}^{n+1}$.

Similar picture for \mathbb{HP}^n , but slightly different for \mathbb{CaP}^2 , since $\nexists S^1 \rightarrow \mathbb{CaP}^2$.

Besides CROSSes, few other examples of closed mflds w/ $\text{sec} > 0$ are known; actually only in dimensions 6, 7, 12, 13, and 24. All of them have large symmetry group... Why?

Grove Symmetry Program: Classify closed mflds w/ $\text{sec} > 0$ and large isometry gps. purposefully vague. Choose your preferred notion.

While attempting to classify, one may also narrow the places to search for new examples; this is how the last example was discovered $T_1 S^4 \# \Sigma^7$.

"Model" result;

It has an isometric action w/ 4-dim. orbit space...

Thm (Hsiang-Kleiner, Grove-Wilking). If (M^4, g) is closed simply-connected with $\text{sec}_g > 0$ and $S^1 \curvearrowright (M^4, g)$ isometric action, then M^4 is (equivariantly) diffeomorphic to S^4 or \mathbb{CP}^2 .

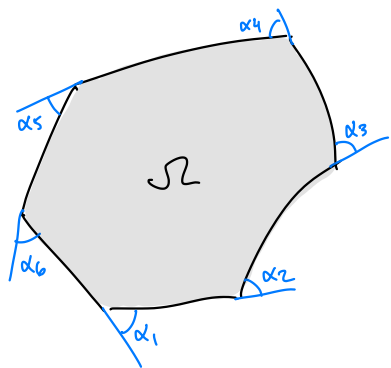
Qual prep

About 49% smooth manifolds, differential forms, etc (1st semester)

49% Riem. geometry (2nd semester)

2% Left overs: Gauss-Bonnet, Lie groups

Recall Gauss-Bonnet: (M^2, g) compact oriented manifold, $\Omega \subset M^2$ compact domain w/ piecewise smooth boundary $\partial\Omega$, then



$$\int_{\Omega} \sec dA + \int_{\partial\Omega} K_g ds = 2\pi \chi(\Omega).$$

$$= \sum_{i=1}^k \int_{\gamma_i} K_g ds + \sum_{i=1}^k \alpha_i$$

If γ has $\|\dot{\gamma}\|=1$, then

$K_g = \|\nabla_{\dot{\gamma}} \dot{\gamma}\|$ so $K_g = 0 \Leftrightarrow \gamma$ is a geodesic.

$dA = \text{vol}_g$ is volume form of (M^2, g)

$ds = \text{arclength along } \partial\Omega$.

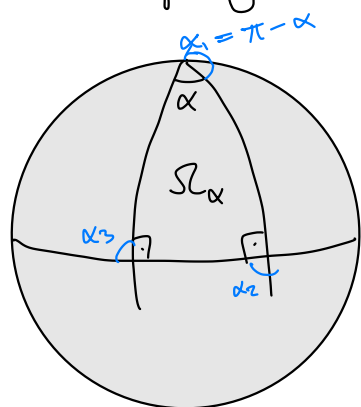
if $\partial\Omega = \gamma_1 \cup \dots \cup \gamma_k$, where α_i is change in angle of tangent vector when moving from γ_i to γ_{i+1} (mod k).

Important cases: $\partial\Omega = \emptyset \quad \int_M \sec dA = 2\pi \chi(M)$

$\partial\Omega$ piecewise geodesic $\int_{\Omega} \sec dA + \sum \alpha_i = 2\pi \chi(\Omega)$

Ex: Spring 2021

#10



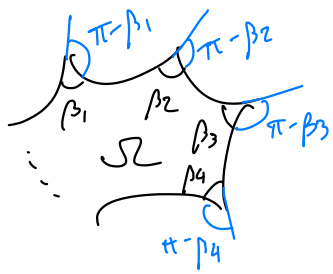
$\Omega_{\alpha} \subset S^2(r)$ is a triangle on the round sphere with $\sec \equiv \frac{1}{r^2}$ and interior angles $\alpha, \frac{\pi}{2}, \frac{\pi}{2}$.

"Verify Gauss-Bonnet?" ① $\partial\Omega_{\alpha}$ is piecewise geodesic

$$\textcircled{2} \int_{\Omega_{\alpha}} \sec dA = \frac{\text{Area}(\Omega_{\alpha})}{r^2} = \frac{\alpha}{2\pi} \frac{\text{Area}(S^2(r))}{2r^2} = \frac{\alpha \cdot 4\pi r^2}{2\pi \cdot 2r^2} = \alpha.$$

$$\textcircled{3} \sum \alpha_i = (\pi - \alpha) + \frac{\pi}{2} + \frac{\pi}{2} = 2\pi - \alpha \quad \textcircled{4} \chi = 1.$$

Spring 2019 #3



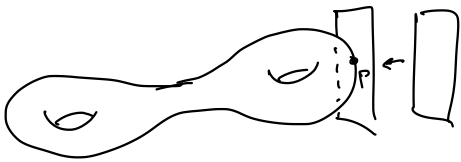
Prove that area of hyperbolic polygon w/ n geodesic sides and interior angles β_i , $1 \leq i \leq n$, is:

$$\text{Area}(\Omega) = (n-2)\pi - \sum_{i=1}^n \beta_i$$

$$\underbrace{\int_{\Omega} \sec dA}_{=-\text{Area}(\Omega)} + \sum_{i=1}^n \alpha_i \underset{\parallel}{=} \sum_{i=1}^n (\pi - \beta_i) = 2\pi \chi(\Omega) = 2\pi \Rightarrow \text{Area}(\Omega) = n\pi - \sum \beta_i - 2\pi.$$

Fall 2022 #10.

Prove that $\Sigma_g^2 \subset \mathbb{R}^3$ w/ genus $g \geq 2$ has an open set with $\sec < 0$ and one with $\sec > 0$.



① $\Sigma_g^2 \subset \mathbb{R}^3$ is closed embedded so $\exists p \in \Sigma_g^2$ at maximal distance from $0 \in \mathbb{R}^3$, and thus $\sec_p > 0$. (bring parallel planes from infinity)

By continuity, $\sec_p > 0$ on $B_\varepsilon(p)$.

② $\int_{\Sigma_g^2} \sec = 2\pi \chi(\Sigma_g^2) = 2\pi(2-2g) < 0$ so $\exists U \subset \Sigma_g^2$ w/ $\text{Area}(U) > 0$ s.t. $\int_U \sec < 0$.

Rmk: If (M^2, g) is complete, noncompact, and $\int_M \sec < +\infty$, then $\int_M \sec \leq 2\pi \chi(M)$.
(e.g., on $M = \mathbb{R}^2$ flat, $0 < 2\pi$.)

Some computational questions:

Fall 2022 #1. Compute \sec of $(\mathbb{R}^2, e^{2f}(dx^2 + dy^2))$ where $f: \mathbb{R}^2 \rightarrow \mathbb{R}$ is smooth.

$X = e^{-f} \frac{\partial}{\partial x}$, $Y = e^{-f} \frac{\partial}{\partial y}$ is global o.n. frame.

$$\begin{aligned} [X, Y]\phi &= XY\phi - YX\phi = e^{-f} \frac{\partial}{\partial x} \left(e^{-f} \frac{\partial \phi}{\partial y} \right) - e^{-f} \frac{\partial}{\partial y} \left(e^{-f} \frac{\partial \phi}{\partial x} \right) \\ &= e^{-f} \left(e^{-f} \left(-\frac{\partial f}{\partial x} \right) \frac{\partial \phi}{\partial y} \right) + e^{-2f} \frac{\partial^2 \phi}{\partial x \partial y} - e^{-f} \left(e^{-f} \left(-\frac{\partial f}{\partial y} \right) \frac{\partial \phi}{\partial x} \right) - e^{-2f} \frac{\partial^2 \phi}{\partial y \partial x} \end{aligned}$$

$$= e^{-2f} \left(\frac{\partial f}{\partial y} \frac{\partial}{\partial x} - \frac{\partial f}{\partial x} \frac{\partial}{\partial y} \right) \phi = e^{-f} \left(\frac{\partial f}{\partial y} X - \frac{\partial f}{\partial x} Y \right) \phi$$

$$\text{so } [X, Y] = e^{-f} \left(\frac{\partial f}{\partial y} X - \frac{\partial f}{\partial x} Y \right).$$

Need

$$\text{sec}(X \wedge Y) = \langle \nabla_X \nabla_Y Y - \nabla_Y \nabla_X Y - \nabla_{[X, Y]} Y, X \rangle$$

By Koszul: $\langle \nabla_Y X, Z \rangle = \frac{1}{2} \left(X(g(Y, Z)) + Y(g(Z, X)) - Z(g(X, Y)) \right.$
these vanish on an orthonormal frame! $\left. - g([X, Z], Y) - g([Y, Z], X) - g([X, Y], Z) \right).$

Before computing a lot---

$$g(X, X) = 1 \quad \text{so} \quad 0 = X g(X, X) = 2 g(\nabla_X X, X)$$

$$0 = Y g(X, X) = 2 g(\nabla_Y X, X)$$

$$g(Y, Y) = 1 \quad \text{so} \quad 0 = X g(Y, Y) = 2 g(\nabla_X Y, Y)$$

$$0 = Y g(Y, Y) = 2 g(\nabla_Y Y, Y)$$

$$g(X, Y) = 0 \quad \text{so} \quad 0 = X g(X, Y) = g(\nabla_X X, Y) + g(X, \nabla_X Y)$$

$$0 = Y g(X, Y) = g(\nabla_Y X, Y) + g(X, \nabla_Y Y)$$

so only need $g(\nabla_X X, Y) = \dots$
 and $g(\nabla_Y X, Y) = \dots$
 to determine $\nabla_X X$
 and $\nabla_Y X$.
 similarly for $\nabla_X Y$
 and $\nabla_Y Y$.

don't need to apply Koszul again

$$\nabla_Y Y = \langle \nabla_Y Y, X \rangle X = \frac{1}{2} \left(-g([Y, X], Y) - g([Y, X], Y) \right) X$$

$$= g\left(e^{-f} \left(\frac{\partial f}{\partial y} X - \frac{\partial f}{\partial x} Y \right), Y\right) X = -e^{-f} \frac{\partial f}{\partial x} X.$$

$$\begin{aligned}\nabla_X X &= \langle \nabla_X X, Y \rangle Y = \frac{1}{2} \left(-g([X, Y], X) - g([X, Y], X) \right) Y \\ &= -g \left(e^{-f} \left(\frac{\partial f}{\partial y} X - \frac{\partial f}{\partial x} Y \right), X \right) Y = -e^{-f} \frac{\partial f}{\partial y} Y\end{aligned}$$

$$\begin{aligned}\nabla_X Y &= \langle \nabla_X Y, X \rangle X = \frac{1}{2} \left(-g([Y, X], X) - g([Y, X], X) \right) X \\ &= g \left(e^{-f} \left(\frac{\partial f}{\partial y} X - \frac{\partial f}{\partial x} Y \right), X \right) X = e^{-f} \frac{\partial f}{\partial y} X.\end{aligned}$$

$$\nabla_Y X = \nabla_X Y + [Y, X] = e^{-f} \frac{\partial f}{\partial y} X - e^{-f} \left(\frac{\partial f}{\partial y} X - \frac{\partial f}{\partial x} Y \right) = e^{-f} \frac{\partial f}{\partial x} Y.$$

$$\begin{aligned}\sec(X \wedge Y) &= \frac{\langle R(X, Y)Y, X \rangle}{\|X\|^2 \|Y\|^2 - \langle X, Y \rangle^2} = \langle \nabla_X \nabla_Y Y - \nabla_Y \nabla_X Y - \nabla_{[X, Y]} Y, X \rangle \\ &= \langle \nabla_X \left(-e^{-f} \frac{\partial f}{\partial x} X \right) - \nabla_Y \left(e^{-f} \frac{\partial f}{\partial y} X \right) - \nabla_{e^{-f} \frac{\partial f}{\partial y} X - e^{-f} \frac{\partial f}{\partial x} Y} Y, X \rangle \\ &= \left\langle -X \left(e^{-f} \frac{\partial f}{\partial x} \right) X - e^{-f} \frac{\partial f}{\partial x} \underbrace{\nabla_X X}_{\text{orthogonal to } X} - Y \left(e^{-f} \frac{\partial f}{\partial y} \right) X - e^{-f} \frac{\partial f}{\partial y} \underbrace{\nabla_Y X}_{\text{orthogonal to } X} \right. \\ &\quad \left. - e^{-f} \frac{\partial f}{\partial y} \nabla_X Y + e^{-f} \frac{\partial f}{\partial x} \nabla_Y Y, X \right\rangle \\ &= -e^{-f} \frac{\partial}{\partial x} \left(e^{-f} \frac{\partial f}{\partial x} \right) - e^{-f} \frac{\partial}{\partial y} \left(e^{-f} \frac{\partial f}{\partial y} \right) - \left(e^{-f} \frac{\partial f}{\partial y} \right)^2 - \left(e^{-f} \frac{\partial f}{\partial x} \right)^2\end{aligned}$$

$$\begin{aligned}
 &= e^{-f} \left(\underbrace{e^{-f} \left(\frac{\partial f}{\partial x} \right)^2}_{\text{}} - e^{-f} \frac{\partial^2 f}{\partial x^2} + \underbrace{e^{-f} \left(\frac{\partial f}{\partial y} \right)^2}_{\text{}} - e^{-f} \frac{\partial^2 f}{\partial y^2} \right) - e^{-2f} \left(\underbrace{\left(\frac{\partial f}{\partial y} \right)^2}_{\text{}} + \underbrace{\left(\frac{\partial f}{\partial x} \right)^2}_{\text{}} \right) \\
 &= e^{-2f} \left(- \frac{\partial^2 f}{\partial x^2} - \frac{\partial^2 f}{\partial y^2} \right) = -e^{-2f} \Delta f.
 \end{aligned}$$

The above is "faster" with a moving frames formalism, but also doable with usual Riem. geom. techniques.

Fall 2002 #7 Compute sec of $(\mathbb{R}^2, dx^2 + e^{2y} dy^2)$; show $x = \text{const}$ are geodesics

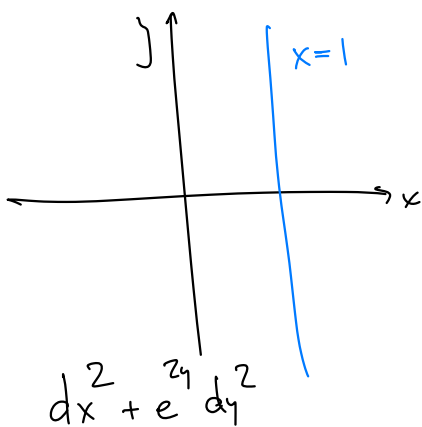
Recall $g = dr^2 + f(r)^2 d\theta^2$ has $\text{sec} = -\frac{f''}{f}$. In the above, we can

use an arclength parameter, $ds^2 = e^{2y} dy^2$, so $\frac{ds}{dy} = e^y$ and

$s(y) = e^y$. Thus, $(\mathbb{R}^2, dx^2 + e^{2y} dy^2)$ is isometric to the flat

upper half-plane $(\mathbb{R}_x(0, +\infty), dx^2 + ds^2)$; in particular,

$\text{sec} \equiv 0$. The curves $x = \text{const.}$ are geodesics b/c they map via the isometry $(x, y) \mapsto (x, e^y)$ to straight lines in the flat upper half plane, which are geodesics.



$$(x, y) \mapsto (x, e^y)$$

$$(x, \ln s) \mapsto (x, s)$$

$$dx^2 + ds^2, \quad s > 0$$

Note:
neither
metric is
complete!