- 1. A point P is represented in the  $(x_1, x_2, x_3)$  system by P(2, 1, 3). Another coordinate system represents the same point as  $P(x'_1, x'_2, x'_3)$  but in a system where  $x_2$  has been rotated towards  $x_3$  around the  $x_1$ -axis by an angle of  $30^{\circ}$ . (i) Find the rotation matrix. (ii) Determine  $P(x'_1, x'_2, x'_3)$ . (iii) Verify that the rotation operator preserves the length of the position vector.
- 2. For the two vectors,  $\vec{a} = \hat{\mathbf{i}} + 2\hat{\mathbf{j}} \hat{k}$  and  $\vec{b} = -2\hat{\mathbf{i}} + 3\hat{\mathbf{j}} + \hat{k}$ , find: (i)  $\vec{a} \vec{b}$ , (ii)  $|\vec{a} \vec{b}|$ , (iii) Component of  $\vec{b}$  along  $\vec{a}$ , (iv) angle between  $\vec{a}$  and  $\vec{b}$ , (v)  $\vec{a} \times \vec{b}$ , and (vi)  $(\vec{a} \vec{b}) \times (\vec{a} + \vec{b})$ .
  - 3. Consider the following matrices:

$$\mathbf{A} = \left(\begin{array}{ccc} 1 & 2 & -1 \\ 0 & 3 & 1 \\ 2 & 0 & 1 \end{array}\right)$$

$$\mathbf{B} = \left(\begin{array}{ccc} 2 & 1 & 0 \\ 0 & -1 & 2 \\ 1 & 1 & 3 \end{array}\right)$$

$$oldsymbol{C} = \left( egin{array}{cc} 2 & 1 \ 4 & 3 \ 1 & 0 \end{array} 
ight)$$

find the following:

- (i) |AB|, (ii) AC, (iii) ABC, and (iv)  $AB B^TA^T$ .
- 4. Show that the product of 2 orthogonal matrices is also an orthogonal matrix.
- 5. Show that:

(i) 
$$\vec{a}$$
 .  $(\vec{b} \times \vec{c}) = \vec{c}$  .  $(\vec{a} \times \vec{b})$ 

$$(ii)\;(\vec{a}\times\vec{b})\;.\;(\vec{c}\times\vec{d})=(\vec{a}\;.\;\vec{c})\;(\vec{b}\;.\;\vec{d})-(\vec{b}\;.\;\vec{c})(\vec{a}\;.\;\vec{d})$$

(iii) 
$$\vec{a}$$
 . ( $\vec{a} \times \vec{c}$ ) = 0

- 6. Show that  $\vec{\nabla}(\ln |\vec{r}|) = \vec{r}/r^2$
- 7. Show that  $\vec{\nabla}(\phi \psi) = \phi \vec{\nabla} \psi + \psi \vec{\nabla} \phi$
- 8. Evaluate the integral

$$\int \vec{a} \times \ddot{\vec{a}} dt$$