A1 Vector Algebra and Calculus

Prof David Murray

david.murray@eng.ox.ac.uk www.robots.ox.ac.uk/~dwm/Courses/2VA

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Vector Algebra and Calculus

- 1 Revision of vector algebra, scalar product, vector product
- 2 Triple products, multiple products, applications to geometry
- 3 Differentiation of vector functions, applications to mechanics
- Scalar and vector fields. Line, surface and volume integrals, curvilinear co-ordinates
- 5 Vector operators grad, div and curl
- 6 Vector Identities, curvilinear co-ordinate systems
- 7 Gauss' and Stokes' Theorems and extensions
- 8 Engineering Applications



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Vector Operators: Grad, Div and Curl

We introduce three field operators which reveal interesting collective field properties, viz.

- the gradient of a scalar field,
- the divergence of a vector field, and
- the **curl** of a vector field.

There are two points to get over about each:

- The mechanics of taking the grad, div or curl, for which you will need to brush up your calculus of several variables.
- The underlying physical meaning that is, why they are worth bothering about.



The gradient of a scalar field

Recall the discussion of temperature distribution, where we wondered how a scalar would vary as we moved off in an arbitrary direction ...

If $U(\mathbf{r})$ is a scalar field, its **gradient** is defined in Cartesians coords by

grad
$$U = \frac{\partial U}{\partial x} \hat{\mathbf{i}} + \frac{\partial U}{\partial y} \hat{\mathbf{j}} + \frac{\partial U}{\partial z} \hat{\mathbf{k}}$$
.

It is usual to define the vector operator ${oldsymbol
abla}$

$$\boldsymbol{\nabla} = \begin{bmatrix} \hat{\mathbf{i}} \ \frac{\partial}{\partial x} \ + \ \hat{\mathbf{j}} \ \frac{\partial}{\partial y} \ + \ \hat{\mathbf{k}} \ \frac{\partial}{\partial z} \end{bmatrix}$$

which is called "del" or "nabla". We can write grad $U \equiv \nabla U$ NB: grad U or ∇U is a **vector** field!

Without thinking too hard, notice that grad U tends to point in the direction of greatest change of the scalar field U

The gradient of a scalar field



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& Examples of gradient evaluation

\$1.
$$U = x^2$$

 $\nabla U = \left[\hat{\mathbf{i}} \frac{\partial}{\partial x} + \hat{\mathbf{j}} \frac{\partial}{\partial y} + \hat{\mathbf{k}} \frac{\partial}{\partial z} \right] x^2$
Only $\partial/\partial x$ exists so
 $\nabla U = 2x\hat{\mathbf{i}}$.

\$2.
$$U = r^2 = x^2 + y^2 + z^2$$
, so
 $\nabla U = \left[\hat{\mathbf{i}} \frac{\partial}{\partial x} + \hat{\mathbf{j}} \frac{\partial}{\partial y} + \hat{\mathbf{k}} \frac{\partial}{\partial z} \right] (x^2 + y^2 + z^2)$
 $= 2x\hat{\mathbf{i}} + 2y\hat{\mathbf{j}} + 2z\hat{\mathbf{k}}$
 $= 2\mathbf{r}.$

\$3. $U = \mathbf{c} \cdot \mathbf{r}$, where **c** is constant.

$$\nabla U = \left[\hat{\mathbf{i}} \frac{\partial}{\partial x} + \hat{\mathbf{j}} \frac{\partial}{\partial y} + \hat{\mathbf{k}} \frac{\partial}{\partial z} \right] (c_1 x + c_2 y + c_3 z)$$
$$= c_1 \hat{\mathbf{i}} + c_2 \hat{\mathbf{j}} + c_3 \hat{\mathbf{k}} = \mathbf{c} \quad .$$

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Another Example ...

4.
$$U = f(r)$$

First, remember this from 1st year? (Don't answer ...)
 $f = f(x, y, z); \quad r = r(x, y, z), \text{ and } f = f(r). \Rightarrow df/dr \text{ exists.}$
 $df = \frac{\partial f}{\partial x}dx + \frac{\partial f}{\partial y}dy + \frac{\partial f}{\partial z}dz \& dr = \frac{\partial r}{\partial x}dx + \frac{\partial r}{\partial y}dy + \frac{\partial r}{\partial z}dz$
 $\Rightarrow \frac{df}{dr} = \frac{\frac{\partial f}{\partial x}dx + \frac{\partial f}{\partial y}dy + \frac{\partial f}{\partial z}dz}{\frac{\partial r}{\partial x}dx + \frac{\partial r}{\partial y}dy + \frac{\partial r}{\partial z}dz}$
But x,y,z are independent, so can choose dx, dy, dz at will and the above expression MUST still hold.
Choose $dz = dy = 0, dx = dz = 0$ then $dx = dy = 0$ in turn ...
 $\frac{df}{dr} = \frac{\partial f}{\partial x}/\frac{\partial r}{\partial x} \qquad \frac{df}{dr} = \frac{\partial f}{\partial y}/\frac{\partial r}{\partial y} \qquad \frac{df}{dr} = \frac{\partial f}{\partial z}/\frac{\partial r}{\partial z}$

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Example /ctd

Now back to our problem:

$$\boldsymbol{\nabla} U = \frac{\partial f}{\partial x}\hat{\mathbf{i}} + \frac{\partial f}{\partial y}\hat{\mathbf{j}} + \frac{\partial f}{\partial z}\hat{\mathbf{k}} = \frac{df}{dr}\left[\frac{\partial r}{\partial x}\hat{\mathbf{i}} + \frac{\partial r}{\partial y}\hat{\mathbf{j}} + \frac{\partial r}{\partial z}\hat{\mathbf{k}}\right]$$

But
$$r = \sqrt{x^2 + y^2 + z^2}$$
, so $\frac{\partial r}{\partial x} = \frac{x}{r}$ and similarly for y, z.

Hence if f = f(r)

$$\Rightarrow \nabla U = \frac{df}{dr} \left[\frac{x \hat{\mathbf{i}} + y \hat{\mathbf{j}} + z \hat{\mathbf{k}}}{r} \right] = \frac{df}{dr} \left[\frac{\mathbf{r}}{r} \right]$$

Note that f(r) is spherically symmetrical and the resultant vector field is radial out of a sphere.

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The significance of grad

We know that the total differential and grad are defined as

$$dU = \frac{\partial U}{\partial x}dx + \frac{\partial U}{\partial y}dy + \frac{\partial U}{\partial z}dz \quad \& \quad \nabla U = \frac{\partial U}{\partial x}\hat{\mathbf{i}} + \frac{\partial U}{\partial y}\hat{\mathbf{j}} + \frac{\partial U}{\partial z}\hat{\mathbf{k}}$$

So, we can rewrite the change in U as

$$dU = \nabla U \cdot (dx\hat{\mathbf{i}} + dy\hat{\mathbf{j}} + dz\hat{\mathbf{k}}) = \nabla U \cdot d\mathbf{r}$$

Conclude that

The gradient $\nabla U \cdot d\mathbf{r}$ is the small change in U when we move by $d\mathbf{r}$. (+ve increase, -ve decrease.)

Significance /ctd

We also know (Lecture 3) that *d***r** has magnitude *ds*. So divide by *ds*

$$\Rightarrow \frac{dU}{ds} = \boldsymbol{\nabla} U \cdot \left[\frac{d\mathbf{r}}{ds}\right]$$



But $d\mathbf{r}/ds$ is a unit vector in the direction of $d\mathbf{r}$.

Conclude that

The gradient

grad U has the property that the rate of change of U wrt distance in any direction $\hat{\mathbf{d}}$ is the projection of grad U onto that direction $\hat{\mathbf{d}}$



Directional derivatives

That is

$$\frac{dU}{ds}(\text{in direction of } \mathbf{\hat{d}}) = \boldsymbol{\nabla} U \cdot \mathbf{\hat{d}}$$

The quantity dU/ds is called a **directional derivative**. In general, a directional derivative

- \blacksquare has a different value for each direction $\boldsymbol{\hat{d}}$
- has no meaning until you specify the direction $\hat{\mathbf{d}}$.

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The gradient ...
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At any point P, grad U

- \blacksquare points in the direction of greatest rate of change of U wrt distance at P, and
- has magnitude equal to the rate of change of *U* wrt distance in that direction.



Grad perpendicular to U constant surface

Think of a surface of constant U — the locus (x, y, z) for U(x, y, z) = const

If we move a tiny amount **within** the surface, that is in any tangential direction, there is no change in U, so dU/ds = 0. So for any $d\mathbf{r}/ds$ in the surface

$$\nabla U \cdot rac{d\mathbf{r}}{ds} = 0$$
 .

Conclusion is that: grad U is NORMAL to a surface of constant U







Surface of constant U



The divergence of a vector field

Let **a** be a vector field:

$$\mathbf{a}(x, y, z) = a_1\hat{\mathbf{i}} + a_2\hat{\mathbf{j}} + a_3\hat{\mathbf{k}}$$

The divergence of \mathbf{a} at any point is defined in Cartesian co-ordinates by

div
$$\mathbf{a} = \frac{\partial a_1}{\partial x} + \frac{\partial a_2}{\partial y} + \frac{\partial a_3}{\partial z}$$

The divergence of a vector field is a scalar field.

We can write div as a scalar product with the ∇ vector differential operator:

div
$$\mathbf{a} \equiv \left[\hat{\mathbf{i}} \ \frac{\partial}{\partial x} \ + \ \hat{\mathbf{j}} \ \frac{\partial}{\partial y} \ + \ \hat{\mathbf{k}} \ \frac{\partial}{\partial z} \right] \cdot \mathbf{a} \equiv \boldsymbol{\nabla} \cdot \mathbf{a}$$



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& Examples of divergence evaluation

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1	xî	1
2	$\mathbf{r}(=x\hat{\mathbf{i}}+y\hat{\mathbf{j}}+z\hat{\mathbf{k}})$	3
3	\mathbf{r}/r^3	0
4	r c	$(\mathbf{r} \cdot \mathbf{c})/r$ where \mathbf{c} is constant

43: div $(r/r^3) = 0$

The x component of \mathbf{r}/r^3 is $x.(x^2 + y^2 + z^2)^{-3/2}$ We need to find $\partial/\partial x$ of it ...

$$\frac{\partial}{\partial x} x \cdot (x^2 + y^2 + z^2)^{-3/2} = 1 \cdot (x^2 + y^2 + z^2)^{-3/2} + x \frac{-3}{2} (x^2 + y^2 + z^2)^{-5/2} \cdot 2x$$
$$= r^{-3} \left(1 - 3x^2 r^{-2}\right)$$

Adding this to similar terms for y and z gives

$$r^{-3}\left(3-3(x^2+y^2+z^2)r^{-2}\right)=r^{-3}\left(3-3\right)=0$$



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The significance of div

Consider vector field $\mathbf{f}(\mathbf{r})$ (eg water flow).

This vector has magnitude equal to the mass of water crossing a unit area perpendicular to the direction of \mathbf{f} per unit time.

Take volume element dV and compute balance of the flow of **f** in and out of dV.

Look at the shaded face on the left The contribution to OUTWARD flux from surface is

 $\mathbf{f}(x, y, z) \cdot d\mathbf{S} = [f_x \hat{\mathbf{i}} + f_y \hat{\mathbf{j}} + f_z \hat{\mathbf{k}}] \cdot (-dx \ dz \ \hat{\mathbf{j}}) = -f_y(x, y, z) dx dz.$





Look at the shaded face on the right ...

A similar contribution, but of opposite sign, will arise from the opposite face ... BUT! we must remember that we have moved along y by an amount dy. So that this OUTWARD amount is

$$\mathbf{f}(x, y + dy, z) \cdot d\mathbf{S} = f_y(x, y + dy, z) dx dz$$
$$= \left(f_y + \frac{\partial f_y}{\partial y} dy\right) dx dz$$



Hence the total outward amount from these two faces is

$$-f_{y}dxdz + \left(f_{y} + \frac{\partial f_{y}}{\partial y}dy\right)dxdz = \frac{\partial f_{y}}{\partial y}dydxdz = \frac{\partial f_{y}}{\partial y}dV$$



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The significance of div /ctd

Repeat: Net efflux from these faces is

$$\frac{\partial f_y}{\partial y} dy dx dz = \frac{\partial f_y}{\partial y} dV$$

Summing the other faces gives a total outward flux $% \left({{{\rm{D}}_{{\rm{A}}}}_{{\rm{A}}}} \right)$

$$\left(\frac{\partial f_x}{\partial x} + \frac{\partial f_y}{\partial y} + \frac{\partial f_z}{\partial z}\right) dV = (\boldsymbol{\nabla} \cdot \mathbf{f}) \ dV$$

Conclusion:

The divergence of a vector field represents the flux generation per unit volume at each point of the field.

The total efflux from a volume is equal to the field divergence integrated over the surface of the volume.





The Laplacian: div (grad U) of a scalar field

grad U of any scalar field U is a vector field. We can take the div of any vector field. \Rightarrow we can certainly compute div (grad U)

$$\nabla \cdot (\nabla U) = \left(\hat{\mathbf{i}} \frac{\partial}{\partial x} + \hat{\mathbf{j}} \frac{\partial}{\partial y} + \hat{\mathbf{k}} \frac{\partial}{\partial z} \right) \cdot \left(\left(\hat{\mathbf{i}} \frac{\partial}{\partial x} + \hat{\mathbf{j}} \frac{\partial}{\partial y} + \hat{\mathbf{k}} \frac{\partial}{\partial z} \right) U \right)$$

$$= \left(\left(\hat{\mathbf{i}} \frac{\partial}{\partial x} + \hat{\mathbf{j}} \frac{\partial}{\partial y} + \hat{\mathbf{k}} \frac{\partial}{\partial z} \right) \cdot \left(\hat{\mathbf{i}} \frac{\partial}{\partial x} + \hat{\mathbf{j}} \frac{\partial}{\partial y} + \hat{\mathbf{k}} \frac{\partial}{\partial z} \right) \right) U$$

$$= \left(\frac{\partial^2 U}{\partial x^2} + \frac{\partial^2 U}{\partial y^2} + \frac{\partial^2 U}{\partial z^2} \right)$$

The operator ∇^2 (del-squared) is called the $\mbox{Laplacian}$

$$\nabla^2 U = \left(\frac{\partial^2}{\partial x^2} + \frac{\partial^2}{\partial y^2} + \frac{\partial^2}{\partial z^2}\right) U$$

Appears in Engineering through, eg, Laplace's equation and Poisson's equation

$$\nabla^2 U = 0$$
 and $\nabla^2 U = \rho$



♣ Examples of $\nabla^2 U$ evaluation

.	U	$\nabla^2 U$
1	$r^2(=x^2+y^2+z^2)$	6
2	xy^2z^3	$2xz^3 + 6xy^2z$
3	1/r	0

Let's check \$3.

$$\begin{aligned} 1/r &= (x^2 + y^2 + z^2)^{-\frac{1}{2}} \\ \Rightarrow \frac{\partial^2}{\partial x^2} (x^2 + y^2 + z^2)^{-\frac{1}{2}} &= \frac{\partial}{\partial x} - x \cdot (x^2 + y^2 + z^2)^{-3/2} \\ &= -(x^2 + y^2 + z^2)^{-3/2} + 3x \cdot x \cdot (x^2 + y^2 + z^2)^{-5/2} \\ &= \frac{1}{r^3} \left(-1 + 3\frac{x^2}{r^2} \right) \end{aligned}$$

Adding up similar terms for y and z

$$\nabla^2 \frac{1}{r} = \frac{1}{r^3} \left(-3 + 3 \frac{(x^2 + y^2 + x^2)}{r^2} \right) = 0$$



The curl of a vector field

So far we have seen the operator ${oldsymbol
abla}$:

- Applied to a scalar field ∇U ; and
- **Dotted** with a vector field $\nabla \cdot \mathbf{a}$.

You are now overwhelmed by irrestible urge to ...

cross it with a vector field

This gives the curl of a vector field

$$\mathbf{\nabla} imes \mathbf{a} \equiv \mathsf{curl}\left(\mathbf{a}\right)$$

We can follow the pseudo-determinant recipe for vector products, so that

$$\boldsymbol{\nabla} \times \mathbf{a} = \begin{vmatrix} \hat{\mathbf{j}} & \hat{\mathbf{j}} & \hat{\mathbf{k}} \\ \frac{\partial}{\partial x} & \frac{\partial}{\partial y} & \frac{\partial}{\partial z} \\ \mathbf{a}_x & \mathbf{a}_y & \mathbf{a}_z \end{vmatrix} = \left(\frac{\partial a_z}{\partial y} - \frac{\partial a_y}{\partial z} \right) \hat{\mathbf{i}} + \left(\frac{\partial a_x}{\partial z} - \frac{\partial a_z}{\partial y} \right) \hat{\mathbf{j}} + \left(\frac{\partial a_y}{\partial x} - \frac{\partial a_x}{\partial y} \right) \hat{\mathbf{k}}$$

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& Examples of curl evaluation

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1	$-y\hat{\mathbf{i}} + x\hat{\mathbf{j}}$	2 ƙ
2	$x^2y^2\hat{\mathbf{k}}$	$2x^2y\hat{\mathbf{i}} - 2xy^2\hat{\mathbf{j}}$

Checking ♣2 ...

$$\nabla \times (x^2 y^2 \hat{\mathbf{k}}) = \begin{vmatrix} \hat{\mathbf{i}} & \hat{\mathbf{j}} & \hat{\mathbf{k}} \\ \partial/\partial x & \partial/\partial y & \partial/\partial z \\ 0 & 0 & x^2 y^2 \end{vmatrix}$$
$$= \hat{\mathbf{i}} x^2 2 y - \hat{\mathbf{j}} 2 x y^2$$
$$= 2 x^2 y \hat{\mathbf{i}} - 2 x y^2 \hat{\mathbf{j}}$$



The signifcance of curl

First example gives a clue ... the field $\mathbf{a} = -y\hat{\mathbf{i}} + x\hat{\mathbf{j}}$ is sketched below.

This field has a curl of $2\hat{\mathbf{k}}$, which is in the r-h screw direction out of the page.

You can also see that a field like this must give a finite value to the line integral around the complete loop $\oint_C \mathbf{a} \cdot d\mathbf{r}$.



The signifcance of curl

Curl is closely related to the line integral around a loop.



- the vorticity, or
- the circulation per unit area in the direction of the area's normal

where

The circulation of a vector field **a** round any closed curve *C* is defined to be $\oint_C \mathbf{a} \cdot d\mathbf{r}$



The significance of curl /ctd

Let's find the circulation round the perimeter of a rectangle dx by dy ...

The fields in the x-direction at bottom and top are

$$a_x(x, y, z)$$
 and $a_x(x, y+dy, z) = a_x + \frac{\partial a_x}{\partial y} dy$

The fields in the y-direction at left and right are

$$a_y(x, y, z)$$
 and $a_y(x+dx, y, z) = a_y + \frac{\partial a_y}{\partial x} dx$

Summing around from the bottom in anticlockwise order

$$dC = +[a_x(x, y, z) \ dx] + [a_y(x+dx, y, z) \ dy] - [a_x(x, y+dy, z) \ dx] - [a_y(x, y, z) \ dy]$$

$$\Rightarrow dC = \left(\frac{\partial a_y}{\partial x} - \frac{\partial a_x}{\partial y}\right) dx dy = (\nabla \times \mathbf{a}) \cdot dx dy \hat{\mathbf{k}} = (\nabla \times \mathbf{a}) \cdot d\mathbf{S}$$





Some definitions involving div, curl and grad

A vector field with zero divergence is said to be solenoidal.

A vector field with zero curl is said to be irrotational.

A scalar field with zero gradient is said to be **constant.**



Summary

Today we've introduced ...

- The gradient of a scalar field
- The divergence of a vector field
- The Laplacian
- The curl of a vector field

We've described the grunt of working these out in Cartesian coordinates \ldots

We've given some insight into what "physical" aspects of fields they relate too.

Worth spending time thinking about these. Vector calculus is the natural language of engineering in 3-space.

